FIXED POINTS OF COMPATIBILITY OF TYPE (β) IN MENGER SPACE

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ABSTRACT

The present paper deals with a common fixed point theorem for six self maps which generalizes the result of Pant and Chauhan [9], using the concept of compatibility of type (β) in Menger space.

Keywords and Phrases: Menger Space, Common Fixed Points, Compatible Maps, Compatible Maps of Type (β). AMS Subject Classification (2000). Primary 47H10, Secondary 54H25

I. INTRODUCTION

Jungck and Rhoades [6] termed a pair of self maps to be coincidentally commuting or equivalently weakly compatible if they commute at their coincidence points. Sessa [13] initiated the tradition of improving commutativity in fixed-point theorems by introducing the notion of weak commuting maps in metric spaces. Jungck [5] soon enlarged this concept to compatible maps. Menger [7] introduced the notion of probabilistic metric space which is a generalization of metric space. It is also of fundamental importance in probabilistic functional analysis. The development of fixed point theory in PM-spaces was due to Schweizer and Sklar [11]. Sehgal and Bharucha-Reid [12] obtained a generalization of Banach Contraction Principle on a complete Menger space which is a milestone in developing fixed-point theory in Menger space.

The notion of compatible mapping in a Menger space has been introduced by Mishra [8]. Cho, Murthy and Stojakovik [1] proposed the concept of compatible maps of type (A) in Menger space and gave some fixed point theorems. Recently, using the concept of compatible mappings of type (A), semi-compatibility and occasionally weak compatibility in Menger space, Jain et. al. [2, 3, 4] proved some interesting fixed point theorems in Menger space. In the sequel, Patel and Patel [10] proved a common fixed point theorem for four compatible maps of type (A) in Menger space by taking a new inequality.

In this paper a fixed point theorem for six self maps has been proved using the concept of mappings of compatibility of type (β). We also gave an example.

II. PRELIMINARIES

Definition 2.1.[7] A mapping $\mathcal{F}: \mathbb{R} \to \mathbb{R}^+$ is called a *distribution* if it is non-decreasing left continuous with

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 $\inf \left\{ \ \textbf{\textit{F}}(t) \ | \ t \in R \ \right\} = 0 \qquad \qquad \text{and} \qquad \qquad \sup \left\{ \ \textbf{\textit{F}}(t) \ | \ t \in R \right\} = 1.$

We shall denote by L the set of all distribution functions while H will always denote the specific distribution function defined by

$$H(t) = \begin{cases} 0 & , \quad t \leq 0 \\ 1 & , \quad t > 0 \end{cases}.$$

Definition 2.2. [2] A mapping $t : [0, 1] \times [0, 1] \rightarrow [0, 1]$ is called a *t-norm* if it satisfies the following conditions :

(t-1) t(a, 1) = a, t(0, 0) = 0;

(t-2) t(a, b) = t(b, a);

(t-3) $t(c, d) \ge t(a, b)$; for $c \ge a, d \ge b$,

(t-4) t(t(a, b), c) = t(a, t(b, c)) for all $a, b, c, d \in [0, 1]$.

Definition 2.3. [2] A *probabilistic metric space (PM-space)* is an ordered pair (X, \mathcal{F}) consisting of a non empty set X and a function $\mathcal{F}: X \times X \to L$, where L is the collection of all distribution functions and the value of \mathcal{F} at $(u, v) \in X \times X$ is represented by $F_{u, v}$. The function $F_{u, v}$ assumed to satisfy the following conditions:

(PM-1) $F_{u,v}(x) = 1$, for all x > 0, if and only if u = v;

(PM-2) $F_{U,V}(0) = 0;$

(PM-3) $F_{u,v} = F_{v,u};$

(PM-4) If $F_{u,v}(x) = 1$ and $F_{v,w}(y) = 1$ then $F_{u,w}(x + y) = 1$,

for all $u, v, w \in X$ and x, y > 0.

Definition 2.4. [2] A *Menger space* is a triplet (X, \mathcal{F} , t) where (X, \mathcal{F}) is a PM-space and t is a t-norm such that the inequality

(PM-5) $F_{u,w}(x + y) \ge t \{F_{u,v}(x), F_{v,w}(y)\}, \text{ for all } u, v, w \in X, x, y \ge 0.$

Definition 2.5. [11] A sequence $\{x_n\}$ in a Menger space (X, \mathcal{F}, t) is said to be *convergent* and *converges to a* point x in X if and only if for each $\varepsilon > 0$ and $\lambda > 0$, there is an integer M(ε , λ) such that

$$F_{X_{n}, X}(\varepsilon) > 1 - \lambda$$
 for all $n \ge M(\varepsilon, \lambda)$

Further the sequence $\{x_n\}$ is said to be *Cauchy sequence* if for $\varepsilon > 0$ and $\lambda > 0$, there is an integer $M(\varepsilon, \lambda)$ such that

 $F_{Xn, Xm}(\epsilon) > 1-\lambda$ for all $m, n \ge M(\epsilon, \lambda)$.

A Menger PM-space (X, \mathcal{F} , t) is said to be *complete* if every Cauchy sequence in X converges to a point in X. A complete metric space can be treated as a complete Menger space in the following way :

Proposition 2.1. [3] If (X, d) is a metric space then the metric d induces mappings $\mathcal{F} : X \times X \to L$, defined by $F_{p,q}(x) = H(x - d(p, q)), p, q \in X$, where

$$H(k) = 0, \quad \text{for } k \le 0 \quad \text{and} \quad H(k) = 1, \quad \text{for } k > 0.$$

Further if, $t : [0,1] \times [0,1] \rightarrow [0,1]$ is defined by $t(a,b) = \min \{a, b\}$. Then (X, \mathcal{F}, t) is a Menger space. It is complete if (X, d) is complete.

The space (X, \mathcal{F}, t) so obtained is called the *induced Menger space*.

Definition 2.6. [6] Self mappings A and S of a Menger space (X, \mathcal{F} , t) are said to be weak compatible if they commute at their coincidence points i.e. Ax = Sx for $x \in X$ implies ASx = SAx.

Definition 2.7. [8] Self mappings A and S of a Menger space (X, **F**, t) are said to be *compatible* if $F_{ASx_n}, SAx_n(x) \rightarrow 1$ for all x > 0, whenever $\{x_n\}$ is a sequence in X such that $Ax_n, Sx_n \rightarrow u$ for some u in X, as $n \rightarrow \infty$.

Definition 2.8. [1] Self maps S and T of a Menger space (X, \mathcal{F} , t) are said to be *compatible of type* (β) if $F_{SSx_n, TTX_n}(x) \rightarrow 1$ for all x > 0, whenever $\{x_n\}$ is a sequence in X such that $Sx_n, Tx_n \rightarrow u$ for some u in X, as $n \rightarrow \infty$.

Definition 2.9. [9] Self maps S and T of a Menger space (X, \mathcal{F} , t) are said to be *semi-compatible* if F_{STx_n} , Tu (x) $\rightarrow 1$ for all x > 0, whenever {x_n} is a sequence in X such that Sx_n , $Tx_n \rightarrow u$ for some u in X, as $n \rightarrow \infty$.

Now, the following example shows that the pair of self maps (I, L) are compatible of type (β) but not-semicompatible.

Example 2.1. Let (X, d) be a metric space where X = [0, 2] and (X, \mathcal{F}, t) be the induced Menger space with

$$F_{x,y} = \frac{t}{t+d(x,y)} \text{ for all } t > 0.$$

Define self maps I and L as follows :

Now, $\lim_{n\to\infty} F_{ILx_n,Lx}(t) = \lim_{n\to\infty} F_{l-\frac{1}{n},l}(t) < 1 \text{ for } t > 0.$

Therefore, (I, L) is not semi-compatible mapping. Thus the pair (I, L) of self maps is compatible of type (β) but not semi-compatible.

Remark 2.2. In view of above example, it follows that the concept of compatible maps of type (β) is more general than that of semi-compatible maps.

Lemma 2.1. [15] Let $\{x_n\}$ be a sequence in a Menger space (X, \mathcal{F}, t) with continuous t-norms t and $t(a, a) \ge a$. If there exists a constant $k \in (0, 1)$ such that $F_{X_n, X_{n+1}}(kt) \ge F_{X_{n-1}, X_n}(t)$ for all $t \ge 0$ and n = 1, 2, 3, ..., then $\{x_n\}$ is a Cauchy sequence in X.

Lemma 2.3. [15] Let (X, \mathcal{F}, t) be a Menger space. If there exists a constant $k \in (0, 1)$ such that

 $F_{x, y}(kt) \ge F_{x, y}(t)$ for all $x, y \in X$ and t > 0, then x = y.

A class of implicit relation. Let Φ be the set of all real continuous functions $\phi: (R^+)^4 \to R$, non-decreasing in the first argument with the property :

a. For u, $v \ge 0$, $\phi(u, v, v, u) \ge 0$ or $\phi(u, v, u, v) \ge 0$ implies that $u \ge v$.

b. $\phi(u, u, 1, 1) \ge 0$ implies that $u \ge 1$.

Example 2.3. Define $\phi(t_1, t_2, t_3, t_4) = 18t_1 - 16t_2 + 8t_3 - 10t_4$. Then $\phi \in \Phi$.

III. MAIN RESULT

Theorem 3.1. Let A, B, L, M, S and T be self mappings on a complete Menger space (X, \mathcal{F}, t) with $t(a, a) \ge a$, for some $a \in [0, 1]$, satisfying :

- $(3.1.1) L(X) \subseteq ST(X), M(X) \subseteq AB(X);$
- (3.1.2) ST(X) and AB(X) are complete subspace of X;
- (3.1.3) either AB or L is continuous;
- (3.1.4) (L, AB) is compatible maps of type (β) and (M, ST) is weak compatible;
- $(3.1.5) \qquad \qquad \text{for some } \phi \in \Phi, \text{ there exists } k \in (0, 1) \text{ such that for } x, y \in X \text{ and } t > 0,$

 $\phi(F_{Lx, My}(kt), F_{ABx, STy}(t), F_{Lx, ABx}(t), F_{My, STy}(kt)) \ge 0$

then A, B, L, M, S and T have a unique common fixed point in X.

Proof. Let $x_0 \in X$. From condition (3.1.1) $\exists x_1, x_2 \in X$ such that

 $\mathbf{L}\mathbf{x}_0 = \mathbf{S}\mathbf{T}\mathbf{x}_1 = \mathbf{y}_0 \quad \text{ and } \quad \mathbf{M}\mathbf{x}_1 = \mathbf{A}\mathbf{B}\mathbf{x}_2 = \mathbf{y}_1.$

Inductively, we can construct sequences $\{x_n\}$ and $\{y_n\}$ in X such that

 $\mathrm{Lx}_{2n} = \mathrm{STx}_{2n+1} = \mathrm{y}_{2n} \qquad \text{and} \qquad \mathrm{Mx}_{2n+1} = \mathrm{ABx}_{2n+2} = \mathrm{y}_{2n+1}$

for n = 0, 1, 2, ...

Step 1. Putting $x = x_{2n}$ and $y = x_{2n+1}$ in (3.1.5), we get

$$\phi(F_{Lx_{2n}}, Mx_{2n+1}(kt), F_{ABx_{2n}}, STx_{2n+1}(t), F_{Lx_{2n}}, ABx_{2n}(t), F_{Mx_{2n+1}}, STx_{2n+1}(kt)) \geq 0.$$

Letting $n \to \infty$, we get

$$\phi(F_{y_{2n}, y_{2n+1}}(kt), F_{y_{2n-1}, y_{2n}}(t), F_{y_{2n}, y_{2n-1}}(t), F_{y_{2n+1}, y_{2n}}(kt)) \ge 0.$$

Using (a), we get

$$F_{y_{2n}, y_{2n+1}}(kt) \ge F_{y_{2n-1}, y_{2n}}(t).$$

Therefore, for all n even or odd, we have

$$F_{y_n, y_{n+1}}(kt) \ge F_{y_{n-1}, y_n}(t).$$

Therefore, by lemma 2.1, $\{y_n\}$ is a Cauchy sequence in X, which is complete.

Hence $\{y_n\} \rightarrow z \in X$. Also its subsequences converges as follows :

 $\{Lx_{2n}\} \rightarrow z, \ \{ABx_{2n}\} \rightarrow z, \ \{Mx_{2n+1}\} \rightarrow z \ \text{and} \ \{STx_{2n+1}\} \rightarrow z.$

Case I. When AB is continuous.

As AB is continuous, $(AB)^2 x_{2n} \rightarrow ABz$ and $(AB)Lx_{2n} \rightarrow ABz$.

As (L, AB) is compatible pair of type (β), so

 $LLx_{2n} \rightarrow (AB)(AB)x_{2n}$ and so $LABx_{2n} \rightarrow ABz$

Step 2. Putting $x = ABx_{2n}$ and $y = x_{2n+1}$ in (3.1.5), we get

$$\phi(F_{LABx_{2n}}, Mx_{2n+1}(kt), F_{ABABx_{2n}}, STx_{2n+1}(t), F_{LABx_{2n}}, ABABx_{2n}(t), F_{Mx_{2n+1}}, STx_{2n+1}(kt)) \ge 0$$

Letting $n \to \infty$, we get

 $\phi(F_{ABz, z}(kt), F_{ABz, z}(t), F_{ABz, ABz}(t), F_{z, z}(kt)) \ge 0$

 $\phi(F_{ABz, z}(kt), F_{ABz, z}(t), 1, 1) \geq 0.$

As $\boldsymbol{\varphi}$ is non-decreasing in the first argument, we have

 $\phi(F_{ABz, z}(kt), F_{ABz, z}(t), 1, 1) \geq 0.$

Using (b), we get

 $F_{ABz, z}(t) = 1$, for all t > 0,

i.e. ABz = z.

Step 3. Putting x = z and $y = x_{2n+1}$ in (3.1.5), we get

$$\phi(F_{Lz, Mx_{2n+1}}(kt), F_{ABz, STx_{2n+1}}(t), F_{Lz, ABz}(t), F_{Mx_{2n+1}, STx_{2n+1}}(kt)) \geq 0.$$

Letting $n \to \infty$, we get

$$\phi(F_{Lz, z}(kt), F_{ABz, z}(t), F_{Lz, ABz}(t), F_{z, z}(kt)) \ge 0$$

$$\phi(F_{LZ, Z}(kt), 1, F_{LZ, Z}(t), 1) \ge 0$$

As $\boldsymbol{\varphi}$ is non-decreasing in the first argument, we have

 $\phi(F_{LZ, Z}(kt), 1, F_{LZ, Z}(t), 1) \ge 0.$

Using (a), we get

 $F_{z, L, z}(kt) = 1$, for all t > 0,

i.e. z = Lz.

Thus, we have z = Lz = ABz.

Step 4. Putting x = Bz and $y = x_{2n+1}$ in (3.1.5), we get

$$\phi(F_{LBZ, MX_{2n+1}}(kt), F_{ABBZ, STX_{2n+1}}(t), F_{LBZ, ABBZ}(t), F_{MX_{2n+1}, STX_{2n}}(kt)) \ge 0.$$

Letting $n \to \infty$, we get

$$\begin{split} &\phi(F_{\text{Bz},\ z}(\text{kt}),\,F_{\text{Bz},\ z}(\text{t}),\,F_{\text{Bz},\ \text{Bz}}(\text{t}),\,F_{\text{z},\ z}(\text{kt}))\geq\ 0\\ &\phi(F_{\text{Bz},\ z}(\text{kt}),\,F_{\text{Bz},\ z}(\text{t}),\,1,\ 1)\geq\ 0. \end{split}$$

As ϕ is non-decreasing in the first argument, we have

 $\phi(F_{Bz, z}(t), F_{Bz, z}(t), 1, 1) \ge 0.$

Using (b), we have

 $F_{Bz, z}(t) = 1$, for all t > 0,

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.03, Issue No. 06, June 2015 ISSN (online): 2348 - 7550 i.e. z = Bz. Since z = ABz, we also have z = Az. Therefore, z = Az = Bz = Lz. **Step 5.** As $L(X) \subseteq ST(X)$, there exists $v \in X$ such that z = Lz = STv.Putting $x = x_{2n}$ and y = v in (3.1.5), we get $\phi(F_{Lx_{2n}}, Mv^{(kt)}, F_{ABx_{2n}}, STv^{(t)}, F_{Lx_{2n}}, ABx_{2n}^{(t)}, F_{Mv}, STv^{(kt)}) \geq 0.$ Letting $n \to \infty$, we get $\phi(F_{z, Mv}(kt), F_{z, STv}(t), F_{z, z}(t), F_{Mv, z}(kt)) \ge 0$ $\phi(F_{z, Mv}(kt), 1, 1, F_{z, Mv}(kt)) \ge 0$ Using (a), we have $F_{z,Mv}(kt) \ge 1$, for all t > 0. Hence, $F_{z,Mv}(t) = 1$. Thus, z = Mv. Therefore, z = Mv = STv. As (M, ST) is weakly compatible, we have STMv = MSTv.Thus, STz = Mz. **Step 6.** Putting $x = x_{2n}$ and y = z in (3.1.5), we get $\phi(F_{Lx_{2n}}, Mz^{(kt)}, F_{ABx_{2n}}, STz^{(t)}, F_{Lx_{2n}}, ABx_{2n}^{(t)}, F_{Mz}, STz^{(kt)}) \ge 0$ Letting $n \to \infty$, we get $\phi(F_{z, Mz}(kt), F_{z, Mz}(t), 1, 1) \ge 0.$ As ϕ is non-decreasing in the first argument, we have $\phi(F_{z, Mz}(t), F_{z, Mz}(t), 1, 1) \ge 0.$ Using (b), we have $F_{z Mz}(t) \ge 1$, for all t > 0. Thus, $F_{z,Mz}(t) = 1$, we have z = Mz = STz.**Step 7.** Putting $x = x_{2n}$ and y = Tz in (3.1.5) and using Step 5, we get $\phi(F_{Lx_{2n}}, MTz^{(kt)}, F_{ABx_{2n}}, STTz^{(t)}, F_{Lx_{2n}}, ABx_{2n}^{(t)}, F_{MTz}, STTz^{(kt)}) \geq 0.$ Letting $n \to \infty$, we get $\phi(F_{Lz, Tz}(kt), F_{z, Tz}(t), F_{z, z}(t), F_{Tz, Tz}(kt)) \geq 0$ $\phi(F_{z, Tz}(kt), F_{z, Tz}(t), 1, 1) \ge 0.$ As ϕ is non-decreasing in the first argument, we have

 $\phi(F_{z, Tz}(t), F_{z, Tz}(t), 1, 1) \ge 0.$

Using (b), we have

 $F_{z,Tz}(t) \ge 1$, for all t > 0.

Thus, $F_{z,Tz}(t) = 1$, we have

z = Tz.

Since Tz = STz, we also have z = Sz.

Hence

Az = Bz = Lz = Mz = Tz = Sz = z.

Hence, the six self maps have a common fixed point in this case.

Case II. When L is continuous.

As L is continuous, $L^{2}x_{2n} \rightarrow Lz$ and $L(AB)x_{2n} \rightarrow Lz$.

As (L, AB) is compatible map of type (β), so

$$LLx_{2n} \rightarrow (AB) (AB)x_{2n}$$
 and $LABx_{2n} \rightarrow ABz$

By uniqueness of limit in Menger space, we have

Lz = ABz.

Step 8. Putting x = z and $y = x_{2n+1}$ in (3.1.5), we get

$$\phi(F_{Lz, Mx_{2n+1}}(kt), F_{ABz, STx_{2n+1}}(t), F_{Lz, ABz}(t), F_{Mx_{2n+1}, STx_{2n+1}}(kt)) \ge 0.$$

Letting $n \to \infty$, we get

$$\begin{split} \phi(F_{LZ, Z}(kt), F_{LZ, Z}(t), F_{LZ, LZ}(t), F_{Z, Z}(kt)) &\geq 0 \\ \phi(F_{LZ, Z}(kt), F_{LZ, Z}(t), 1, 1) &\geq 0. \end{split}$$

As ϕ is non-decreasing in the first argument, we have

$$\phi(F_{LZ, Z}(t), F_{LZ, Z}(t), 1, 1) \ge 0.$$

Using (b), we have

 $F_{z, Lz}(t) \ge 1$, for all t > 0.

Thus, $F_{z, Lz}(t) = 1$

 \Rightarrow z = Lz.

Therefore,

z = Lz = ABz.

Step 9. Putting x = Bz and $y = x_{2n+1}$ in (3.1.5), we get

 $\phi(F_{LBz,\ Mx_{2n+1}}(kt),\ F_{ABBz,\ STx_{2n+1}}(t),\ F_{LBz,\ ABBz}(t),\ F_{Mx_{2n+1},\ STx_{2n+1}}(kt))\geq\ 0.$

Letting $n \to \infty$, we get

 $\phi(F_{Bz, z}(kt), F_{Bz, z}(t), F_{Bz, Bz}(t), F_{z, z}(kt)) \ge 0$

 $\phi(F_{BZ, z}(kt), F_{BZ, z}(t), 1, 1) \ge 0.$

As ϕ is non-decreasing in the first argument, we have

$$\phi(F_{Bz, z}(t), F_{Bz, z}(t), 1, 1) \ge 0$$

Using (b), we have

 $F_{Bz, z}(t) \ge 1$, for all t > 0.

Thus, $F_{Bz, z}(t) = 1$

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.03, Issue No. 06, June 2015 ISSN (online): 2348 - 7550 z = Bz. \Rightarrow Since z = ABz, we also have z = Az. Therefore, z = Az = Bz = Lz.**Step 10.** As $L(X) \subseteq ST(X)$, there exists $v \in X$ such that z = Lz = STv.Putting $x = x_{2n}$ and y = v in (3.1.5), we get $\phi(F_{Lx_{2n}, Mv}(kt), F_{ABx_{2n}, STv}(t), F_{Lx_{2n}, ABx_{2n}}(t), F_{Mv, STv}(kt)) \geq 0.$ Letting $n \to \infty$, we get $\phi(F_{z, Mv}(kt), F_{z, STv}(t), F_{z, z}(t), F_{Mv, z}(kt)) \ge 0$ $\phi(F_{z, Mv}(kt), 1, 1, F_{z, Mv}(kt)) \ge 0$ Using (a), we have $F_{z My}(kt) \ge 1$, for all t > 0. Hence, $F_{z,Mv}(t) = 1$. Thus, z = Mv. Therefore, z = Mv = STv. As (M, ST) is weakly compatible, we have STMv = MSTv.Thus, STz = Mz. **Step 11.** Putting $x = x_{2n}$ and y = z in (3.1.5), we get $\phi(F_{Lx_{2n}}, Mz(kt), F_{ABx_{2n}}, STz(t), F_{Lx_{2n}}, ABx_{2n}(t), F_{Mz}, STz(kt)) \ge 0$ Letting $n \to \infty$, we get $\phi(F_{z,\ Mz}(kt),\ F_{z,\ Mz}(t),\ 1,\ 1)\geq\ 0.$ As ϕ is non-decreasing in the first argument, we have $\phi(F_{z, Mz}(t), F_{z, Mz}(t), 1, 1) \ge 0.$ Using (b), we have $F_{z, Mz}(t) \ge 1$, for all t > 0. Thus, $F_{z,Mz}(t) = 1$, we have z = Mz = STz.**Step 12.** Putting $x = x_{2n}$ and y = Tz in (3.1.5) and using Step 5, we get $\phi(F_{Lx_{2n}}, MTz^{(kt)}, F_{ABx_{2n}}, STTz^{(t)}, F_{Lx_{2n}}, ABx_{2n}^{(t)}, F_{MTz}, STTz^{(kt)}) \geq 0.$ Letting $n \to \infty$, we get $\phi(F_{L,z_1,T,z}(kt), F_{z_1,T,z}(t), F_{z_2,Z}(t), F_{T,z_1,T,z}(kt)) \ge 0$ $\phi(F_{z, Tz}(kt), F_{z, Tz}(t), 1, 1) \ge 0.$

As ϕ is non-decreasing in the first argument, we have

 $\phi(F_{z, Tz}(kt), F_{z, Tz}(t), 1, 1) \ge 0.$

Using (b), we have

$International Journal of Advanced Technology in Engineering and Science & www.ijates.com \\ Volume No.03, Issue No. 06, June 2015 & ISSN (online): 2348 - 7550 \\ F_{z, Tz}(t) \geq 1, \text{ for all } t > 0. \\$

Thus, $F_{z,Tz}(t) = 1$, we have

$$z = Tz$$
.

Since Tz = STz, we also have z = Sz.

Hence Az = Bz = Lz = Mz = Tz = Sz = z.

Hence, the six self maps have a common fixed point in this case also.

Uniqueness. Let w be another common fixed point of A, B, L, M, S and T; then w = Aw = Bw = Lw = Mw = Sw = Tw.

Putting x = z and y = w in (3.1.5), we get

 $\phi(F_{Lz, Mw}(kt), F_{ABz, STw}(t), F_{Lz, ABz}(t), F_{Mw, STw}(kt)) \ge 0$

$$\phi(F_{Z, W}(kt), F_{Z, W}(t), F_{Z, Z}(t), F_{W, W}(kt)) \ge 0$$

$$\phi(F_{z, w}(kt), F_{z, w}(t), 1, 1) \ge 0.$$

As $\boldsymbol{\varphi}$ is non-decreasing in the first argument, we have

$$\phi(\mathbf{F}_{\mathbf{Z}}, \mathbf{w}(t), \mathbf{F}_{\mathbf{Z}}, \mathbf{w}(t), 1, 1) \ge 0.$$

Using (b), we have

 $F_{z,w}(t) \ge 1$, for all t > 0.

z = w.

Thus, $F_{z, w}(t) = 1$,

i.e.,

Therefore, z is a unique common fixed point of A, B, L, M, S & T.

This completes the proof.

Remark 3.1. The above theorem is a generalization of the result of Pant et. al. [9] in the sense that the condition of semi-compatibility has been replaced by compatibility of type (β).

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