

AN INTEGRATION OF WIND – PV GENERATOR WITH ENERGY STORAGE SYSTEMS

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ABSTRACT

Environmentally friendly solutions are becoming more prominent than ever as a result of concern regarding the state of our deteriorating planet. This paper presents a new system configuration of the front end rectifier stage for a hybrid wind/photovoltaic energy system. This configuration allows the two sources to supply the load separately or simultaneously depending on the availability of the energy sources. There is no need for additional input filters to eliminate the high frequency harmonics, because the PV cell is operated by the new converter. The fused multi-input rectifier stage also allows Maximum Power Point Tracking (MPPT) to be used to extract maximum power from the wind and sun when it is available. An adaptive MPPT algorithm will be used for the wind system and a standard perturb and observe method will be used for the PV system. Operational analysis of the proposed system will be discussed in this paper. Simulation results are given to highlight the merits of the proposed circuit.

I. INTRODUCTION

Renewable energy technologies offer the promise to clean, abundant energy gathered from self – renewing resources such as sun, wind, water, earth and plants. Virtually all regions of the world have renewable resources of one type or another. Renewable energy technologies offer important benefits compared to those of conventional energy sources. Worldwide, 1000 times more energy reaches the surface of the earth from the sun than is released today by all fossil fuels consumed. PV and wind generation are also an attractive source of energy because of their benign effect on the environment. When a source is unavailable or insufficient in meeting the load demands, the other energy source can compensate for the difference. Several hybrid wind/PV power systems with MPPT control have been proposed and discussed in works [1]-[5]. Most of the systems in literature use a separate DC/DC boost converter connected in parallel in the rectifier stage as shown in Figure 1 to perform the MPPT control for each of the renewable energy power sources [1]-[4]. A simpler multi-input structure has been suggested by [5] that combines the sources from the DC-end while still achieving MPPT for each renewable source. The structure proposed by [5] is a fusion of the buck and buck-boost converter.

In this paper, an alternative multi-input rectifier structure is proposed for hybrid wind/solar energy systems. The proposed design is a fusion of the Cuk and SEPIC converters. The features of the proposed topology are: 1) the inherent nature of these two converters eliminates the need for separate input filters for PFC [7]-[8]; 2) it can support step up/down operations for each renewable source (can support wide ranges of PV and wind input); 3) MPPT can be

realized for each source; 4) individual and simultaneous operation is supported. The circuit operating principles will be discussed in this paper. Simulation results are provided to verify with the feasibility of the proposed system.

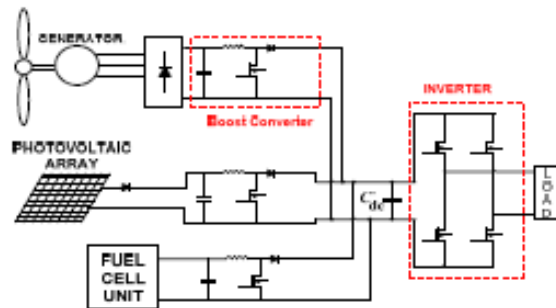


Fig 1: Hybrid system with multi-connected boost converter

II. PROPOSED MULTI-INPUT RECTIFIER STAGE

A system diagram of the proposed rectifier stage of a hybrid energy system is shown in Figure 2, where one of the inputs is connected to the output of the PV array and the other input connected to the output of a generator. The fusion of the two converters is achieved by reconfiguring the two existing diodes from each converter and the shared utilization of the Cuk output inductor by the converter. This configuration allows each converter to operate normally individually in the event that one source is unavailable. Figure 3 illustrates the case when only the wind source is available. In this case, D1 turns off and D2 turns on; the proposed circuit becomes a CUK converter and the input to output voltage relationship is given by (1). On the other hand, if only the PV source is available, then D2 turns off and D1 will always be on and the circuit becomes a Cuk converter as shown in Figure 4. The input to output voltage relationship is given by (2). In both cases, both converters have step-up/down capability, which provide more design flexibility in the system if duty ratio control is utilized to perform MPPT control.

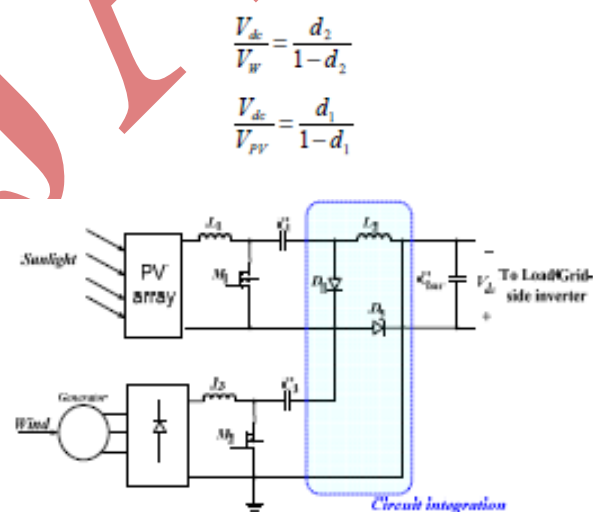


Fig 2: Proposed rectifier stage for a Hybrid wind/PV system

III. ANALYSIS OF PROPOSED CIRCUIT

To find an expression for the output DC bus voltage, V_{dc} , the volt-balance of the output inductor, L_2 , is examined according to Figure 6 with $d_2 > d_1$. Since the net change in the voltage of L_2 is zero, applying volt-balance to L_2 results in (3). The expression that relates the average output DC voltage (V_{dc}) to the capacitor voltages (v_{c1} and v_{c2}) is then obtained as shown in (4), where v_{c1} and v_{c2} can then be obtained by applying volt-balance to L_1 and L_3 [9]. The final expression that relates the average output voltage and the two input sources (V_W and V_{PV}) is then given by (5). It is observed that V_{dc} is simply the sum of the two output voltages of the Cuk and SEPIC converter. This further implies that V_{dc} can be controlled by d_1 and d_2 individually or simultaneously.

$$(v_{c1} + v_{c2})d_1T_s + (v_{c2})(d_2 - d_1)T_s + (1 - d_2)(-V_{dc})T_s = 0$$

$$V_{dc} = \left(\frac{d_1}{1 - d_2} \right) v_{c1} + \left(\frac{d_2}{1 - d_2} \right) v_{c2}$$

$$V_{dc} = \left(\frac{d_1}{1 - d_1} \right) V_{PV} + \left(\frac{d_2}{1 - d_2} \right) V_W$$

The switches voltage and current characteristics are also provided in this section. The voltage stress is given by equations respectively. As for the current stress, it is observed from Figure 6 that the peak current always occurs at the end of the on-time of the MOSFET. Both the Cuk MOSFET current consists of both the input current and the capacitors (C_1 or C_2) current. The peak current stress of M1 and M2 are given by equations respectively. I_{eq1} and I_{eq2} , given by (9) and (11), represent the equivalent inductance of Cuk and CUK converter respectively.

$$v_{ds1} = V_{PV} \left(1 + \frac{d_1}{1 - d_1} \right)$$

$$v_{ds2} = V_W \left(1 + \frac{d_2}{1 - d_2} \right)$$

$$i_{ds1, pk} = I_{i, PV} + I_{dc, avg} + \frac{V_{PV} d_1 T_s}{2L_{eq1}}$$

$$L_{eq1} = \frac{L_1 L_2}{L_1 + L_2}$$

$$i_{ds2, pk} = I_{i, W} + I_{dc, avg} + \frac{V_W d_2 T_s}{2L_{eq2}}$$

$$L_{eq2} = \frac{L_3 L_2}{L_3 + L_2}$$

$$I_{i, PV} = \frac{P_o}{V_{dc}} \frac{d_1}{1 - d_1}$$

IV. MPPT CONTROL OF PROPOSED CIRCUIT

A common inherent drawback of wind and PV systems is the intermittent nature of their energy sources. Wind energy is capable of supplying large amounts of power but its presence is highly unpredictable as it can be here one moment and gone in another. Solar energy is present throughout the day, but the solar irradiation levels vary due to sun intensity and unpredictable shadows cast by clouds, birds, trees, etc. These drawbacks tend to make these renewable systems inefficient. However, by incorporating maximum power point tracking (MPPT) algorithms, the systems' power transfer efficiency can be improved significantly. To describe a wind turbine's power characteristic, equation describes the mechanical power that is generated by the wind [6].

$$P_m = 0.5 \rho A C_p(\lambda, \beta) v_w^3$$

The power coefficient (C_p) is a nonlinear function that represents the efficiency of the wind turbine to convert wind energy into mechanical energy. It is dependent on two variables, the tip speed ratio (TSR) and the pitch angle. The TSR, λ , refers to a ratio of the turbine angular speed over the wind speed. The mathematical representation of the TSR is given by equation [10]. The pitch angle, β , refers to the angle in which the turbine blades are aligned with respect to its longitudinal axis.

$$\lambda = \frac{R \omega_b}{v_w}$$

Figure 3 are illustrations of a power coefficient curve and power curve for a typical fixed pitch ($\beta = 0$) horizontal axis wind turbine. It can be seen from figure 3 that the power curves for each wind speed has a shape similar to that of the power coefficient curve. Because the TSR is a ratio between the turbine rotational speed and the wind speed, it follows that each wind speed would have a different corresponding optimal rotational speed that gives the optimal TSR. For each turbine there is an optimal TSR value that corresponds to a maximum value of the power coefficient ($C_{p,max}$) and therefore the maximum power. Therefore by controlling rotational speed, (by means of adjusting the electrical loading of the turbine generator) maximum power can be obtained for different wind speeds.

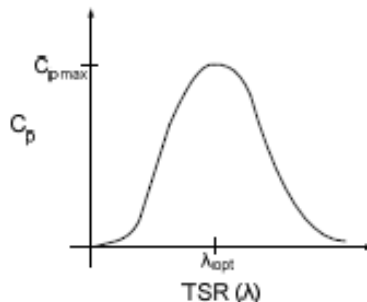


Fig 3: Power Coefficient Curve for a typical wind turbine

A solar cell is comprised of a P-N junction semiconductor that produces currents via the photovoltaic effect. PV arrays are constructed by placing numerous solar cells connected in series and in parallel [5]. A PV cell is a diode of a large-area forward bias with a photovoltage and the equivalent circuit is shown by Figure 4 [11]. The current-voltage characteristic of a solar cell is derived in [12] and [13] as follows:

$$I = I_{ph} - I_D$$

$$I = I_{ph} - I_0 \left[\exp \left(\frac{q(V + R_s I)}{A k_B T} \right) - 1 \right] - \frac{V + R_s I}{R_{sh}}$$

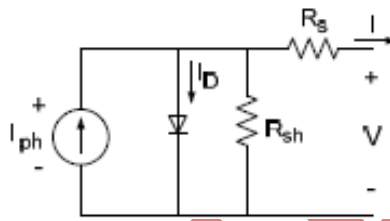


Fig 4: PV cell equivalent circuit

Typically, the shunt resistance (R_{sh}) is very large and the series resistance (R_s) is very small [5]. Therefore, it is common to neglect these resistances in order to simplify the solar cell model. The resultant ideal voltage-current characteristic of a photovoltaic cell is given by (17) and illustrated by Fig 5. [5]

$$I = I_{ph} - I_0 \left(\exp \left(\frac{qV}{kT} \right) - 1 \right)$$

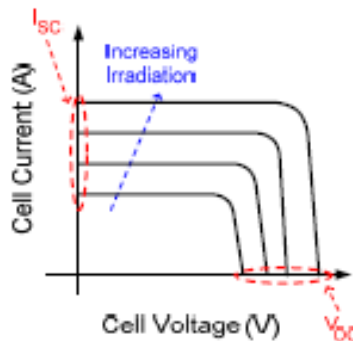


Fig 5: PV cell voltage-current characteristic

Due to the similarities of the shape of the wind and PV array power curves, a similar maximum power point tracking scheme known as the hill climb search (HCS) strategy is often applied to these energy sources to extract maximum power. The HCS strategy perturbs the operating point of the system and observes the output. If the direction of the perturbation (e.g. an increase or decrease in the output voltage of a PV array) results in a positive

The MPPT scheme employed in this paper is a version of the HCS strategy. Figure 6 is the flow chart that illustrates the implemented MPPT scheme.

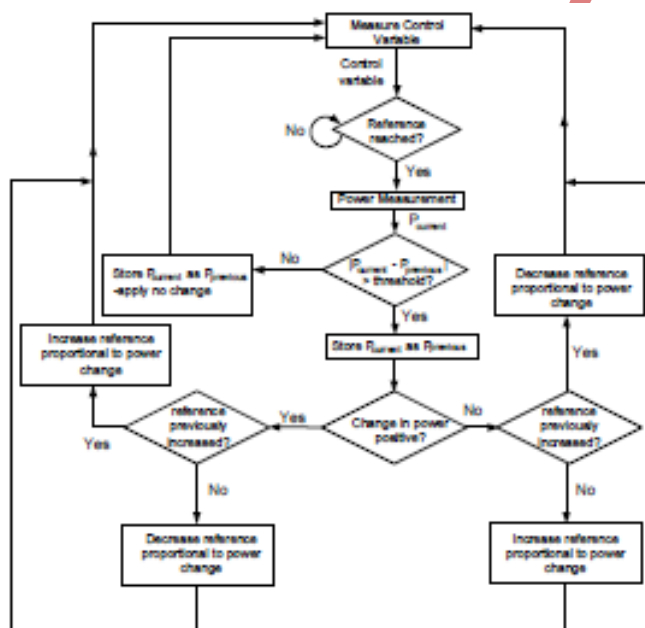


Fig 6: General MPPT Flow Chart for wind and PV

V. SIMULATION RESULTS

In this section, simulation results from PSIM 8.0.7 is given to verify that the proposed multi-input rectifier stage can support individual as well as simultaneous operation. The specifications for the design example are given in TABLE I. Figure 7 illustrates the system under the condition where the wind source has failed and only the PV source (Cuk converter mode) is supplying power to the load. Figure 8 illustrates the system where only the wind turbine generates power to the load.

Output power (w)	3kw
Output voltage	500v
switching frequency	20khz

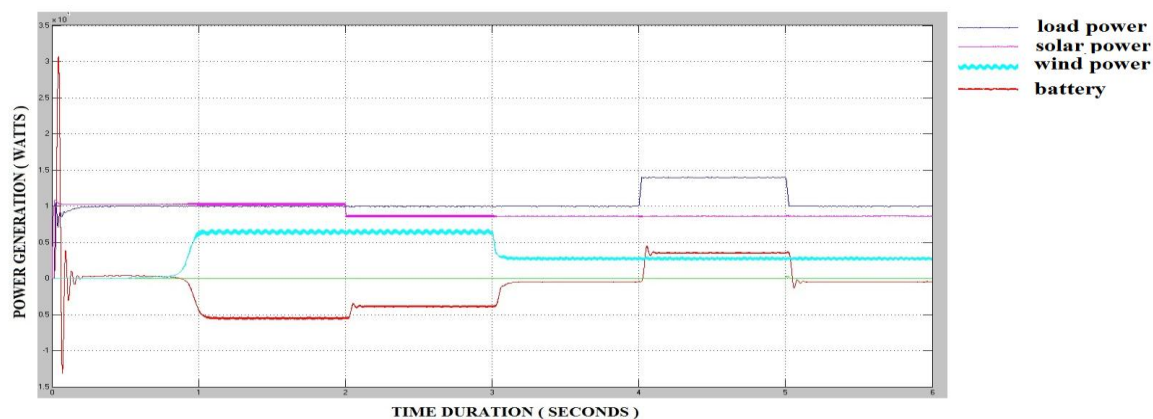


Fig 7 LoadSharing Action Performed by the theHybrid EnergyEnergy in Solar Panel

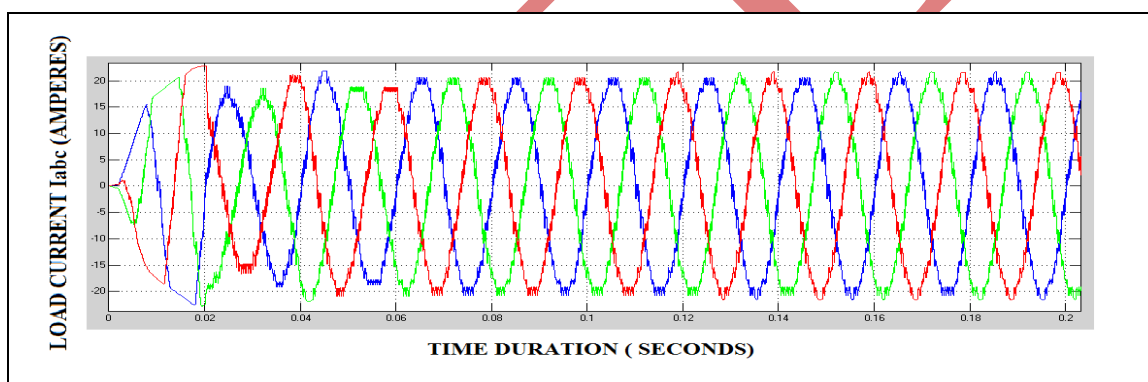


Fig 8The load current supplied to the load is sinusoidal in nature as depicted in the simulation

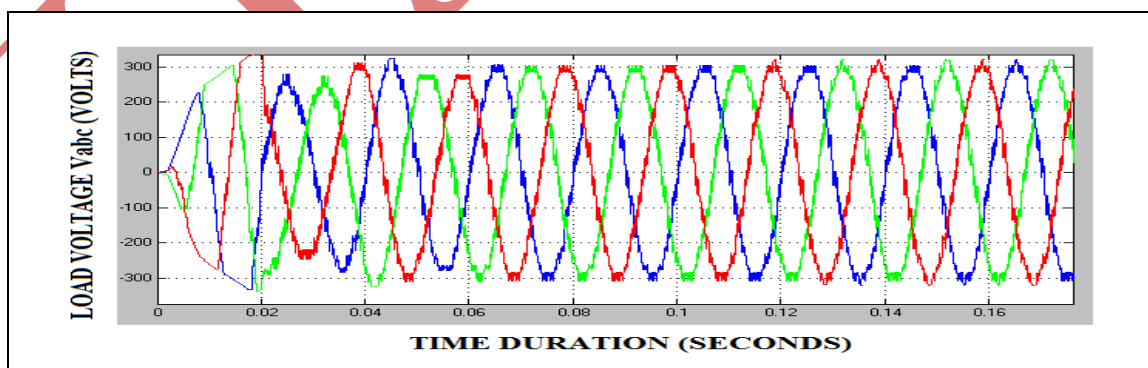


Fig 9 Three Phase Voltage Supplied To The Load By The Inverter

VI. CONCLUSION

In the thesis load demand is met from the combination of PV array, wind turbine and the battery. An inverter is used to convert output from solar & wind systems into AC power output. Circuit Breaker is used to connect an additional load of 5 KW in the given time. This hybrid system is controlled to give maximum output power under all operating conditions to meet the load. Either wind or solar system is supported by the battery to meet the load. Also, simultaneous operation of wind and solar system is supported by battery for the same load.

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