

# ANALYSIS OF THE PROCESSING MODELS OF COMPUTING

**JOBY JOSEPH<sup>1</sup>, C JOTHI VENKATESWARAN<sup>2</sup>, A CLEMENT KING<sup>3</sup>**

<sup>1</sup>Research Scholar, Bharath University, Chennai (India)

<sup>2</sup>Professor, Presidency College, Chennai (India)

<sup>3</sup>Associate Professor, King Khalid University (Saudi Arabia)

## ABSTRACT

*There are many computing models that are in use. Each model has its own advantages for its time. But as the processing requirements grew exponentially, the need for faster processing computing models have been evolving, supported by improved hardware support and novel architecture models. While most models have brought about high degree of parallelism and scalability, some issues of bottleneck still need to be addressed. The paper is an attempt to study these popular models and make a critical analysis of their performance, scalability and parallelism.*

**Keywords:** *Distributed Computing, Cluster Computing, Grid Computing, Cloud Computing*

## I. INTRODUCTION

This chapter takes up a detailed analysis of the various processing models explained in the previous chapter. Beginning with the analysis of the initial single mode of processing, multi-processing, multi-programming models and then proceeds to look at the advanced models of computing like client-server architecture, distributed architecture, cluster computing, grid computing and the advanced model of cloud computing. The last part of the chapter is the discussion in detail about the Cloud Architecture along with the performance analysis.

## II. VARIOUS COMPUTING MODELS

The earliest style of computing was the Single-Processor computing model that allowed *single-user-uni-programming* computational environment. The single process computing environment allowed only limited CPU power in keeping with the availability of the technology. The constraints that limited processing were from CPU power and the computing environment [1]. In most the initial models of computing did not make an effective use of the related resources of the computer. This was primarily due to the difference performance speed between the CPU and the resources attached to the system [2]. This led to long idle time for CPU while waiting for slow peripherals.

An improvement to the uni-programming style was from the introduction of the batch stream operation. Here multiple-jobs could be submitted and the system would handle each job executing each in sequence [2]. The processor utilization was as in the case of single process systems as they were engaged totally while they reported a zero level utilization between intervals of batch processes or while awaiting resource responses. The degree of parallelism reported is nil as in single process systems. The complexity function for the processing is  $O(n)$ , where  $n$  is the number of tasks arriving into the batch processing model [3-5]. The introduction of multi-processing mode of computing was an

addition to the efficiency and speed factor of processing. As the multi-processing uses more than single processor to carry out a given job, it brought notable computing efficiency into the performance matrix with respect to time and parallelism as compared to the preceding models [6].

The most commonly used multi-processing style was the Multiple Instruction Stream Multiple Data Stream (MIMD) model of computing as suggested by Flynn in 1966 [4]. As MIMD came into execution in computing systems, they were realized in two styles as a shared memory model or as a message passing model. The architectural diagrams are shown below:



Figure 1: (a) Shared Memory MIMD Model, (b) Message Passing MIMD Model

Both of these models come with their own advantages and disadvantages. The Shared memory provided common programming and execution while the latter provided better scalability. A trade off between the two had to be achieved while choosing an effective model [7]. Critically analysing, the model promises a better result than the single and batch processing model. There is a degree of parallelism achieved as multiple processors are able to handle higher number of jobs. As all resources like memory, I/O devices etc. are shared by all the processors, there is a need of a proper scheduling of the different CPUs to take the maximum advantages to achieve high degree of parallelism using methods like device synchronization, semaphores, locks etc. But their overlay often outplays the scalability achieved [6-7].

As Amdahl's law states, the maximum expected improvement in overall speed, parallelism and processor usage is limited. According to this law the expected speed up on the parallelized implementation of an algorithm in relation to a non-parallelised algorithm is given as: For an algorithm  $m$  having only 20% parallelizable section, the maximum speed up will be given as  $1/(1-0.2)$ , which is 1.25 factor faster than a non-parallelized version of the same. Hence the improvement achieved is a maximum of 25% [3, 5, 8]. The concept of multiprogramming came in next with the aim of bringing the concept of increased processor utilization. This was to be achieved by avoiding idling time of processors and related resources [9, 10]. The multiprogramming set up allowed execution of more than one applications concurrently thus giving the apparent feel that each application owns its own processor and resources [11].

The architecture is achieved through either time sharing the processor in a uniprocessor environment or space-sharing the processor among the different programs in a multi-processor environment [12]. A number of studies have calibrated the performance of both time sharing and space sharing models of architectures. Andrew Tuckerr *et al* [13] has shown in the research results that in the case of time sharing, it degrades performance at the level of the processors, cache and related resource. And study by Cathy McCann *et al* [14] was a comparative study of both the above policies in performance. Their result showed that a better rating of space sharing policy over the time sharing model of multi programming. The former reported according to them a better utilization of the processor and resource power.

### III. DISTRIBUTED COMPUTING

As computing world looked at better models of realizing scalability and processing speed distributed style of computing become a promising mode. A performance analysis of this model is brought out in the coming section. The aim of the distributed model is to keep the utilization index always at the optimum. The index should be below the possible utilization bound [15]. In the Distributed Computing architecture the great gain was that jobs could be switched and moved idle processors or workstations. Such task migration from overloaded workstations to idle processors improves better processor utilization. According Ioana *et al* [3]. The increase of processor number does not necessarily provide guaranteed linear growth of performance through put[4].

The next analysis considered is with respect to processor idle time and parallelism. The chief goal of a distributed architecture is to realize “economic efficiency” in the use resources, idle time thus bringing high degree of parallelism [16]. According to performance results observed by Jinokim [11], the improvement on distributed models can be rated to a factor of 63% as compared to normal systems in the same setup. The experiment was done with respect to a greedy based parallel downloading that used 10 blocks of data each of 4 MB. The result reports that there is an increase in the parallel dimension of the execution. The experiments of Kotsis [17] also notes a notable improvement in the parallelism point of the system. The factor that left unattended is the idle time of the distributed system. An element of resource and processor underutilization is reported side by side.

### IV. CLIENT-SERVER COMPUTING

In the pursuit of higher degree of parallelism and efficiency, the new model of Client-Server architecture of processing came to the front. An analysis of this model of processing is done in this section. The C-S model of information processing allowed the unique characteristic of co-operative computing facility that allows to physically split the processing job into Client’s role and the Server’s role, but presenting to the user a unified model of data processing [18 -19]. The performance matrix of C-S model can reveal lot of interesting results. There is no doubt that it promises a higher degree of parallelism and distributed computation that occurs across the clients or the servers allowing substantial increase in the efficiency of the processing model. However, the models did also throw up some crunches when real data of results are viewed.

As indicated by the experiment of Barry, there is an overhead of 15 minutes time, used for data transfer when the processing is done over the clients. Hence compared to the server execution of the same process, there will be an additional overtime of 15 min, when the job is over the clients. This reported overhead is spent on the network traffic as many clients get into the array of processing. The overlay of client delay time and idle time are high over the C-S model. The degree of parallelism has scaled up when considered to other uniprocessor models of computing [20,21].

## V. CLUSTER COMPUTING

Though the concept of cluster computing was an old concept as back in 1960, it gained the momentum in 1980s. The factors that added up to this are the release of high performance microprocessors, high speed network devices and an environment standard which supported distributed computing. The concept of cluster computing has brought to the IT arena even common PCs as cost effective processing modules giving the architecture a notable degree of parallelism and computational power [22]. In the context of this promise, there is a need of analysing the performance of the cluster model against set bench marks of processor and resource utilization, parallelism and idle time in processing. In most recent cluster configurations use Symmetric Multiprocessors (SMPs) and high bandwidth connections interconnecting these clusters nodes. These allow low latency and high bandwidth connection. Here is a performance report of the CPU utilization index and related performance values.

The configuration that supports best results allotment and utilization is the SSI(Single System Image), where the distributive and heterogeneous nature of the resources is apparently hidden from the user and it virtually presents as a single entity- like a unified powerful single system. Though this configuration allows high degree of availability and scalability of nodes, there is often underutilization of processors and resources within the cluster [23]. Though there is a saving and economy on configuration the overall processor utilization here is poor. According to the observed results of Buyya *et al* [23], there is 70-90% idle time for a node for the node processors. According to other observed results, under low end and high end cluster there is often the happening of cross migration of jobs across processors. These are reported in Buyaa *et al* [23] and are due to heavy load on processors or availability of free processors within the cluster [23,24].

According to the results of Henry [24], the cluster model exhibits a weak scalability and parallelism. According to their observed results, a cluster shows an increased level of scalability at minimum value. The experiment of Henry was done on a NCSA-1024 processors PIII/1 GHz Linux Cluster. The results reported a weak scalability factor as shown in the table below:

S.No.	Number of Processors	Scalability Index
1.	1	2
2.	2	2.5
3.	4	2.7

Table 1.1 Performance index of Cluster Computing

From the above table, it is clear that the growth of scalability is very minimal and there is still room for a higher degree of parallelism and cluster scalability. Coming to the issue of parallelism and idle time, as observed by Buyaa *et al* in their experiments [23], there is a maximum factor of 70-90% workstation and resource underutilization. Most CPU cycles go wasted in the cluster configuration as reported by Baker *et al* in their experiment [25]. There is a factor that can be introduced to take care of these idle time basing on the unused CPU cycles [ 23,24]. As the aim of the cluster configuration is to achieve linear speed up in processing- implying to achieve a speed up factor equal to

the number of processors in the cluster. The ideal according to Henry Neuman [26] is to achieve the linear speed up, but very few cluster configurations attain this level of parallelism.

## VI. VIRTUALIZED GRID COMPUTING

The Grid computing model consists of the availability of resources and processing power over a virtualized environment [27]. In the section that follows is a performance analysis of the Virtualized Grid system architecture with respect to the processor and resource utilization, degree of parallelism and idle time management. As Grid computing is a technology fully realized and executed in Virtualization, the performance evaluation will also take care of the factors that affect virtualized computing. An accurate performance evaluation of the Grid model will involve many parameters and considerations. There exists too many performance evaluation indices done over the efficiency of the Grid structure. Various researches have rated the performance under various category. In keeping with the interest of the research, the section studies the performance against the factors of concern. The study and result of Radu Prodan *et al* [28] is more about the performance of the workflow and other various overheads involved in the grid. But basing on the analysis of Naixue Xiong *et al* [29], the focus is to make a shift to incorporate best admission control algorithm for the jobs and also improve the computing performance thereby with full utilization of the CPU cycles. This is expected to avoid overloading and under loading of the system. According to their observations and results, it is reported a CPU utilization of 60 – 70%. The results according to Xiong [29] are reported in table below:

Sl. No	Time in Seconds	CPU Utilization Ratio in Percentage
1.	0 - 50	30 – 80%
2.	50 - 100	45 – 75%
3.	100 – 150	60 - 65%

Table 1.2: CPU Utilization in Grid Computing

Regarding the resource utilization over the Grid, the study and results of Stefan Krawczyk *et al* [30], can give some light. The experiment is with the varying number of users against a number of resources that are available. According to the results observed by Krawczyk the best performance achieved is while with the single user and as the number of users increase – a definite minimal decline in performance index and resource utilization is noticed. But overall there is an element of consistency [29], [30]. The details of the results are shown in the table below:

Sl. No	Number of Users	Time in Seconds	Percentage of Utilization
1.	1	0 - 500	0 – 55%
		500 - 1000	55 – 65%
2.	5	0 - 500	0 – 85%
		500 - 1000	85 – 93%

Table 1.3: Performance index of Resource Utilization Grid Computing

The next concern is the degree of parallelism and idle time in the virtualized grid configuration. According to the experiments by Krawczyk [30], the waiting time reported is high. This could be because of the reason that the policy of satisfying all requests. According to the best scheduler suggested by the experiments there is a reduction in the amount of idle time, the queuing time depending up on the arrival scheme used for the jobs in the architecture. The details are produced below in the table 1.4:

Sl. No	Arrival Scheme	Average Waiting Time in Percentile (Scale of 1 – 10)
1.	Random Auction	3
2.	Volunteer Schedule	6
3.	Auction on Load	4
4.	Waiting Auction	8.5

Table 1.4: Job Arrival schemes and their mean performance in Grid Architecture

In order to rate the parallelism of the Grid, the experiment and performance evaluation performed by Dario *et al* [27] can be considered. According to their observed results, when the grid is highly loaded, the parallel performance is reportedly good. If the job arrival rate reported is 0.0032 job/sec, the observed parallelism is commendable. As the configuration gets saturated and jobs have an arrival rate of 0.0044/sec, then there is reportedly a drop in the parallel performance of the system. Hence, the degree of parallelism can be boosted in the grid virtual environment. An introduction of a novel processing style can bring this factor.

## V. CLOUD COMPUTING

The Cloud Architecture is a commercial infrastructure set up that promises computing services at different levels to the clients. It is a Service Oriented Architecture that is gaining wide coverage and acceptability in the world of Information Technology [31]. In the Cloud Architecture of computing, there is the full realization of virtualization that makes resources, platforms and infrastructure available as a service [31,32]. Though there are many Cloud Providers available in the world, the real choice of one for the need of high end scientific researchers is a hard one to find. The many available cloud providers need to be really analysed against their performance indices to rate and make a choice of any for higher computing [31,3332]. In Cloud environment resources like files, programmes, data streams, platforms and even the very hardware itself is made accessible to the clients [34]. The QoS has to be rated best since it is often a pricing and service model.

As reported by Alexandru Ioasup [31] *et al*, the bottleneck problem of the Cloud Architecture is a real issue. In most cases, it is a CPU, I/O Device or memory that stands on the way of higher level of efficiency and parallelism. In the light of interest of the research, the focus is on the Cloud Architecture as one with a realm of infinite computing possibilities. The performance indices available in two common cloud models are analysed to arrive at their actual efficiency. In the sections that follow, a detailed study is done on Amazon EC2 and Google Cloud. In the case of Amazon EC2, the CPU utilization reported is very minimal. The performance analysis reported by Alexandru [31] is a

substantial proof to this. In the Amazon EC set up, the user is allowed to stretch or shrink the infrastructure needed by starting or ending a virtual service called the *Instance*. The set up allows a maximum of 20 such instances for a user [79]. According to the observed results of Alexandru, the average CPU utilization is of very low index in the Amazon set up. The EC2 system architecture does not even allocate additional free and unutilized CPU cycles to waiting processes or users. In contrast, if there is a sanction of 100% of CPU power to a user, there exists no provision of giving back the extra and unwanted the CPU control [31 - 32]. The table 3.8 gives the performance indices of the Amazon EC2 cloud against CPU utilization [31].

Sl. No	Number of CPUs	Performance Efficiency in Percentage
1.	1	10 %
2.	2	20 %
3.	4	25 %
4.	8	45 %

Table 1.5: CPU performance indices for Amazon EC2

In the case of the Google Cloud, the utilization of CPU power is explained in the parts that follow. According to the performance analysis of Sheng Di *et al* [35] there is lot of notable observations available from the CPU utilization statistics of the Google cloud. The scheduling of jobs submitted and the resource management with respect these jobs and CPU allocation to these jobs are based on a high-priority basis. According to the results available with Sheng [35], over 25 million jobs are distributed over 12500 large systems within a month. The parameters concerning the CPU usage and other resource allocation are of interest to our research. The CPU utilization is done by finding the ratio of the collective execution time on one or more processors against the total time as:

$$\text{CPU Use} = (\text{No. of CPUs}) \times \text{Executing time per CPU} / \text{total time taken}$$

In the Google Cloud the reported CPU usage is comparatively less [83]. Basing on the results of Sheng, the observed overall usage is only 35% with respect to all the tasks in hand. With respect to resource utilization and idle time, the Google cloud reports high degree of idle time, while the memory and other related resources testify to the usage of 80% of the total availability. The degree of parallelization realized in Google cloud remains low as the maximum usage of the CPUs is not realized.

## VII. CONCLUSION

The paper presented against each model of computing, its respective performance indices. The data reported are basing on the existing research results. As there is an incremental growth in the processing achieved, there are performance issues and efficiency that are often left out. In the light of the analysis of the various computing models, the focus is to look into this factor of efficiency, so that while processing speed is achieved, the optimum performance is met at every level from the architecture of the model.



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