

THE DESIGN OF MICROWAVE OSCILLATOR BY THE METHOD OF NEGATIVE RESISTANCE

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ABSTRACT

An electronic oscillator is an electronic circuit that produces a periodic, oscillating electronic signal, often a sine wave or a square wave. Oscillators convert direct current (DC) from a power supply to an alternating current signal. A lower phase-noise of the oscillator means less interference between channels and that a smaller frequency band is needed for the same data rate. For high frequency systems, power output level and efficiency are always meaningful for reducing amplifier demands and extending the battery life of mobile systems. Microwave oscillator was selected because their wide use in commercial, space and defence systems where demanding performance, high reliability and cost are critical. This products take advantage of the small size, low phase noise and high efficiency with the help of low phase noise amplifiers and Dielectric Resonators. Low phase-noise oscillators make systems utilize channels more effectively. For the requirement of low phase-noise, a GaAs FET amplifier was used as the active device, for its low phase –noise and high performance at microwave frequency of 2.5. GHz.

Keywords: Low Phase Noise, Microwave Oscillator, High Quality Factor, Simulation, Negative Resistance.

I. INTRODUCTION

In this paper we deal with the low phase noise in microwave oscillator. The phase noise of the oscillator is achieved by increasing the loaded quality factor. Here we use Advanced System Design software to achieve the simulation. The Bipolar Transistor circuit is selected to perform the simulation of the oscillator. In this note, the design on a 2.5 GHz bipolar oscillator by the method of negative resistance is used.

II. HEADINGS

In the negative resistance oscillator design, the negative resistors can be realized easily by a three terminals active device with proper feedback. This negative resistor is used to cancel out the lost from the resonator.

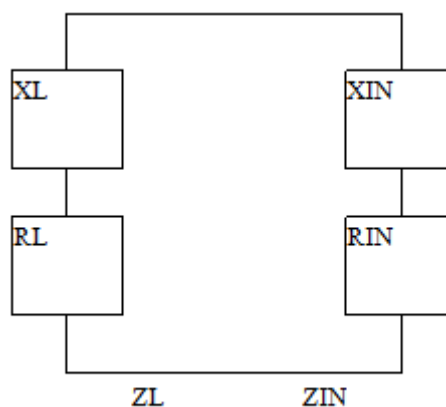


Fig.1 Negative Resistance Oscillator

The figure above (Fig. 1) shows a typical negative resistance oscillator. First, it is necessary to make sure the overall circuit to be unstable such that:

$$RIN \square \square RL \square \square 0 \dots \dots \dots (1)$$

When a stable oscillation occurs, the following conditions must be satisfied:

$$RIN \square \square RL \square \square 0 \dots \dots \dots (2)$$

$$XIN \square \square XL \square \square 0 \dots \dots \dots (3)$$

Base on the theory above, a negative resistance will be designed and simulated in ADS to satisfy equation (1) and a resonator will be designed and simulated in ADS to satisfy equation (2) and (3).

Finally, the combined circuit will be simulated in ADS by the method of harmonic balance to see the overall performance the oscillator.

II. IDENTATIONS AND EQUATIONS

Leeson took oscillators as linear time invariant feedback systems. Leeson's phase noise model of feedback oscillator is shown in Fig. 1. The oscillator can be seen as an amplifier which has feedback through a filter. If the gain is sufficient to overcome the filter attenuation and the phase shift is correct, oscillation will occur [11-12].

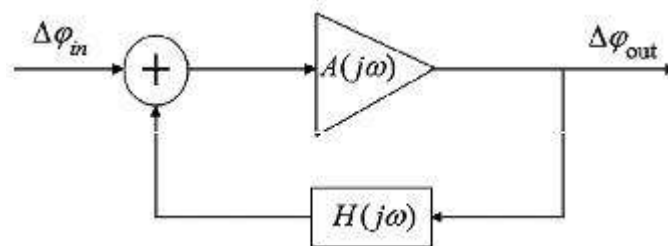


Fig. 1 Leeson's Phase Noise Model of Feedback Oscillator.

The Leeson formula below is derived from the phase noise model of Leeson shown in Fig. 1:

$$L(f_m) \square \square \frac{1}{2} \left[\frac{f_0}{f} \right]^2 \frac{F k T}{P} \frac{1}{Q^2 L} \dots \dots \dots (1)$$

Where f_m is offset frequency, f_0 is center frequency, QL is loaded quality factor, f_c is corner frequency for flicker noise, F is noise factor, k is Boltzmann constant, T is absolute temperature, P is the carrier power, and $L(f_m)$ is the power spectral density of the output phase noise. By the analysis of (1), it can be seen that phase noise has a direct relation with noise factor F , corner frequency f_c and loaded quality factor QL . Therefore, there are three methods to reduce phase noise.

One method to reduce phase noise is to decrease the noise factor F . Noise factor F is decided by many factors. To reduce phase noise by decreasing the noise factor F is not easy to realize. Because noise factor F of low phase noise transistor circuit is very low currently, phase noise can be reduced about 1-3 dB by negative feedback methods, the effect is not obvious.

Another method to reduce phase noise based on Leeson model is to decrease corner frequency f_c . The corner frequency of transistor has a direct impact on the phase noise. To decrease the corner frequency of transistor is

needed to greatly improve integrated circuit technology level, and its influence on phase noise cannot be reduced effectively using the method of external circuit. Now low noise bipolar transistor's corner frequency f_c generally has fallen to 3-5 KHz. If f_c is decreased to 1-2 KHz, near carrier frequency phase noise can be reduced about 2 dB, the effect also is not obvious.

The third method is to reduce phase noise by improving loaded quality factor QL . The quality factor actually indicates phase noise characteristics. It not only affects the structure of the phase noise spectral density, but also affects the intensity of phase noise. Improving unloaded quality factor is restricted by physics and materials. From (1), we can draw a conclusion that near carrier frequency phase noise improves with increasing QL . So a high QL is beneficial to reducing near carrier frequency phase noise.

Based on above analysis, we can draw a conclusion that QL is the main effect factor of phase noise, so it is feasible to reduce phase noise by improving QL .

2.1 Biasing Circuit

Before we start the design, a suitable transistor should be selected and provided a suitable dc bias (Fig.6). In this design, the Agilent Technologies High Performance Isolated Collector Silicon Bipolar Transistor HBF0450 will be used. It will be biased to operate at 2V VCE and 20mA IC. The model of the transistor used in the simulation can be found in ADS component library (Fig. 5). In this simulation, the DC simulator in ADS is used to make sure the required biasing condition is obtained.

2.2 Negative Resistance

After designed the biasing circuit, the transistor will be constructed as a common emitter capacitive feedback circuit. This will produce a negative resistance in order to cancel the lost from the resonator. In this simulation, the S-Param simulator in ADS is used of the circuit. From the simulation result, it shows that the overall resistance of the circuit is zero near 2.5 GHz and satisfies the equation 2.

2.3 S-Parameter (S_Param) Simulator

The S_param simulator is used to find the circuit parameters such as s-, z- and y- parameters. The start and stop frequency of the wanted parameter is required by the simulator (Fig. 3). Besides, a circuit termination should be added in the circuit schematic as the measurement port of the circuit. It is used to find the input impedance of the active device in the negative resistance design and used to check the three oscillation condition equations in the resonator design.

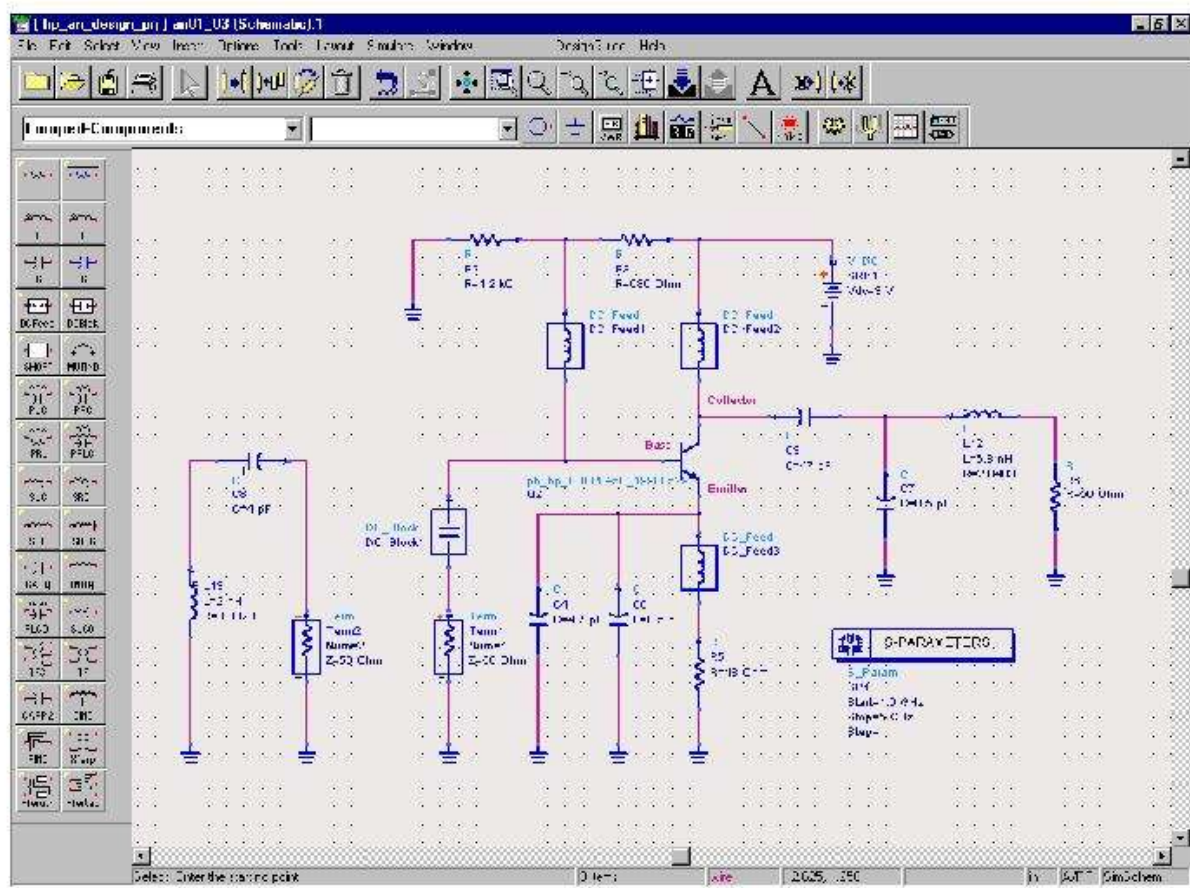
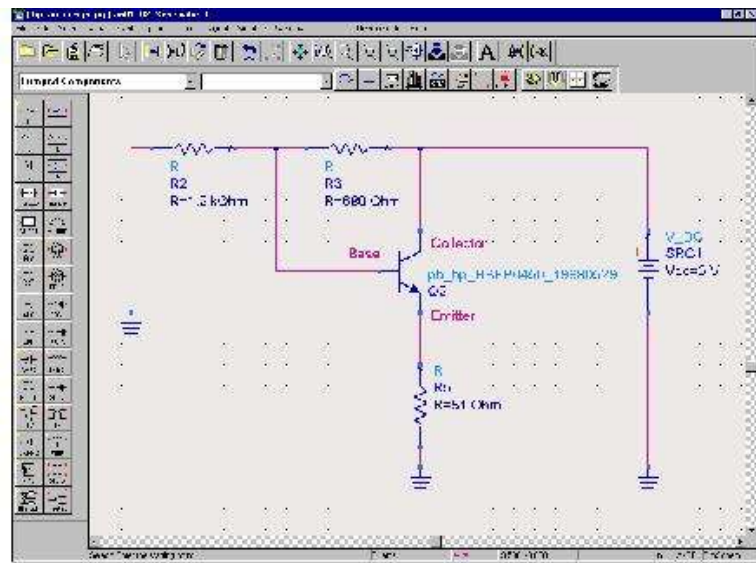
Fig. 3 S_param simulator

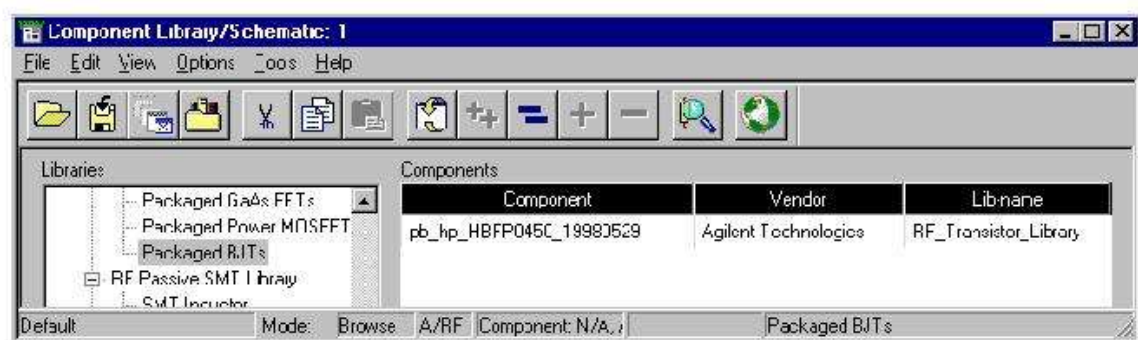
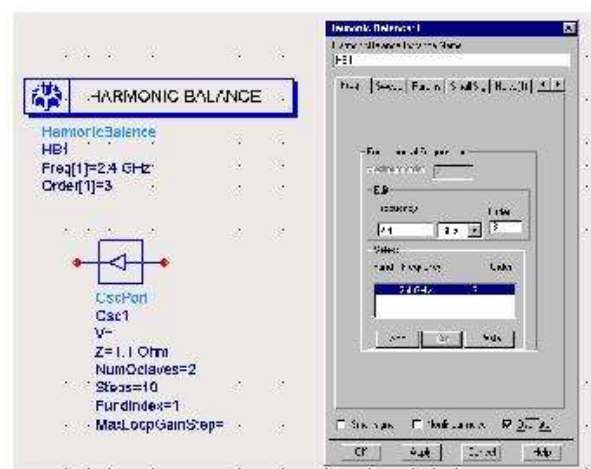
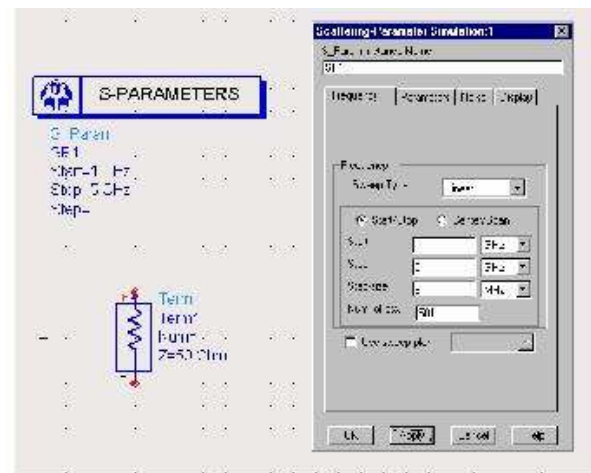
2.4 Harmonic Balance (HB) Simulator

The HB simulator is used to simulate the performance of the oscillator. In this simulator, the expected fundamental frequency is required. Besides, an osc-port component is added in the circuit schematic. The osc-port should be placed such that it separates the negative- resistance portion of the oscillator from the resonator portion. The arrow should point in the direction of the negative resistance.

This simulator is used in the final evaluation of the oscillation circuit.

III. FIGURES AND TABLES





IV. CONCLUSION

In this application note, a typical negative resistance oscillator designed by using the advanced circuit simulator ADS is resented. By using a powerful simulator, the design time can be greatly reduced and engineers can achieve circuit performance before the implementation of circuit.

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