# PERFORMANCE ANALYSIS AND OPTIMIZATION OF AN M/M/3 QUEUEING SYSTEM UNDER TETRAD POLICY

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#### **ABSTRACT**

In this paper, we consider machine repair problem with three removable repairmen which is adjusted one at a time depending upon the number of broken machines in the M/M/3 queueing system with finite capacity L operating under the tetrad policy. In this system, the repairman is not available for serving the failed units, when the number of failed units is less than N. We derive the probability generating function (PGF) of the number of failed units waiting in the system. The total expected cost function per unit time is derived to calculate the operating optimal tetrad policy at minimum cost. Along with this Sensitive analysis and direct search algorithm on the optimum value also performed. In the end, some numerical examples are presented to show the influence of the system parameters on performance measures.

Keywords: Broken Machines, Cost Control. Tetrad Policy, M/M/3 Queueing System

### 1. INTRODUCTION

We consider an M/M/3 queuing system where the number of operating service stations (or repairmen) can be adjusted one at a time at customer's arrival or service completion epochs depending on the number of failed units present in the system under steady-state conditions. Hahn and Sivazlian [4] introduced this model for M/M/2 at the indistinguishable service stations. The concept of a (0, N) policy in the controllable M/M/I system was first introduced by Yadin and Naor [8]. An operating policy is called the (0, N) policy if the number of customers in the system reaches N, where  $N \ge 1$  for the first time after the server is removed from the system, the server returns immediately and provides service until there are no customers present in the system. Bell [1], Magazine [9], Sobel [10], and others concentrated on developing the optimal operating policy of the controllable systems under various assumptions regarding the distributions of interarrival and service times.

Gnedenko *et al.* [3] had studied the reliability of a single-server 2-unit warm standby system with exponential failure and general repair time distributions. Gopalan [7] investigated the reliability of a single-server n-unit system with (n-1) warm standbys with an exponential failure time distribution and two types of general repair time distributions of the operating unit and of the standbys.

The four main objectives for which the analysis has been carried out in this paper are:

- i. To determine the steady state probability distribution of the number of units in the system.
- ii. To derive expected number of units in the system.

iii. To formulate the total expected cost function for the system, and determine the optimal value of the control parameter N.

iv. To carryout sensitivity analysis on the optimal value of N and the minimum expected cost through numerical illustrations.

#### 2. DESCRIPTION OF THE MODEL

#### 2.1. DEFINITION OF THE OPERATING POLICY:

The special feature of operating policy of this M/M/3 queuing system of finite capacity L under the tetrad  $\{0, (Q, R), N, M, K\}$  policy is that the number of the operating repairmen can always be adjusted based on the number of broken machines in the system. Thus, the number of broken machines in the system is monitored at every new failed machine's arrival and service completion epochs. Whenever there are no failed machines in the system, repairmen are in vacations temporarily, and may not be reactivated until certain condition is satisfied. We discuss the states of the system by the pairs (i, n), i = 0, 1, 2, 3, n = 0, 1, 2, ..., Q, ..., R, ..., N, ..., M, ..., K, ..., L, where <math>i = 0 denotes that the repairmen are on temporally vacations, i = 1 denotes that one of the repairmen working in the system, i = 3 denotes that all the three repairmen are active and working in the system and n is the number of failed machines in the system.

### **2.2 EQUATIONS GOVERNING THE SYSTEM:**

Consider the probabilities used in the system

P(0,n) = probability that the there is no active repairmen in the system and there are n customers in the system, where n = 0, 1, 2, 3, ... N-1,

P(1,n) = probability that the there is one active repairmen in the system and there are n customers in the system, where n = 0, 1, 2, 3, ...

Q,...R,...N,...M-1,

P(2,n) = probability that the there is two active repairmen in the system and there are n customers in the system, where n = Q + 1, Q + 2,...R, R + 1, ..., N,...M,...K - 1,

 $P(3,n) = \text{probability that the there is three active repairmen in the system and there are n customers in the system, where <math>n = R + 1, \dots, R + 2, \dots, N, \dots, M, \dots, K, \dots, L$ 

### 2.3 NOTATIONS:

 $\lambda$  = arrival rate exponentially distributed,

 $\mu$  = service rate exponentially distributed,

 $F_0(z)$  = probability generating functions, when there is no active repairmen in the system,

 $F_1(z)$  = probability generating functions, when there is one active repairmen in the system,

 $F_2(z)$  = probability generating functions, when there is two active repairmen in the system,

 $F_3(z)$  = probability generating functions, when there is three active repairmen in the system,

 $P_0$  = probability that all the repairmen are on vacation,

 $P_1$  = probability that one of the repairmen is active and working in the system,

 $P_2$  = probability that two of the repairmen are active and working in the system,

 $P_3$  = probability that all the repairmen are active and working in the system,

 $L_0$  = the expected number of failed machines in the system when all the three repairmen are on vacations,

 $L_1$  = the expected number of failed machines in the system when any one of the repairman working in the system,

 $L_2$  = the expected number of failed machines in the system when two of the repairmen working in the system,

 $L_3$  = the expected number of failed machines in the system when all the three repairmen working in the system,

 $L_s$  = the expected number of failed machines in the system,

C<sub>h</sub> = holding cost per unit time per failed unit present in the system,

 $C_{vl}$  = holding cost per unit time when one repairman is on vacations,

 $C_{v2}$  = holding cost per unit time when two repairmen are on vacations,

 $C_{v3}$  = holding cost per unit time when all the repairmen are on vacations,

 $C_{01}$  = cost of one repairman working in the system per unit time,

 $C_{02}$  = cost of two repairmen working in the system per unit time,

 $C_{03} = \cos t$  of three repairmen working in the system per unit time,

#### 2.4 STATE- TRANSITION-RATE DIAGRAM

The probabilities P(i, n) where i = 0, 1, 2, 3 and n is the number of failed unit in the system, of the arrival and departure of the served unit are shown through the state-transition diagram for the controllable  $M\backslash M\backslash 3$  queueing system with finite capacity L under the tetrad  $\{0, 0, 0, M, K\}$  policy.

### **Number of working servers**

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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$				P(0,0)	0
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$\begin{array}{c ccccccccccccccccccccccccccccccccccc$			P(1,Q-1)	P(0,Q-1)	Q-1
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$\begin{array}{c ccccc} & & & & & & & & & & & & & & & & &$		2 <del>µ</del>	· /	P(0,Q)	Q
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P(2,Q+2)		<i> </i>	P(1,Q+1)	P(0,Q+1)	Q+1
P(2,Q+2)		$2\mu$ $\lambda$	μ λ	λ	
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	P(2,R-1) 2μ λ	P(1,R-1)	P(0,R-1)	R-1
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		$\begin{pmatrix} \mu & \lambda \end{pmatrix}$	λ	
→ P(3,R+1) —	P(2,R+1)	P(1,R+1)	P(0,R+1)	R+1
$3\mu$ $\lambda$	$2\mu$ $\lambda$	(μ λ	λ	
P(3,R+2)	P(2,R+2)	P(1,R+2)	P(0,R+2)	R+2
$\lambda$	$\sqrt{2\mu}$ $\lambda$	(μ λ	λ	
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$(3\mu \lambda)$	$\left(\begin{array}{cc} 2\mu & \lambda \end{array}\right)$	μ λ	λ	
P(3,N-2)	P(2,N-2)	P(1 N-2) 4	P(0,N-2)	N-2
$(3\mu \lambda)$	$2\mu$ $\lambda$	μ λ	λ	
P(3,N-1)	P(2,N-1)	P(1,N-1)	P(0,N-1)	N-1
$3\mu$ $\lambda$	$(2\mu \lambda)$	$\mu$ $\lambda$	λ	
P(3,N)	P(2,N) 4	P(1,N)		N
3μ λ	$(2\mu \lambda)$	μλ		
P(3,N+1)	P(2,N+1)	P(1,N+1)		N+1
$3\mu$ $\lambda$	$2\mu$ $\lambda$	(μ λ		
P(3,N+2)	P(2,N+2)	P(1,N+2)		N+2
$3\mu$ $\lambda$	2μ. λ	(μ λ <sub>.</sub> )		
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$3\mu$ $\lambda_{4}$	2μ λ <sub>2</sub>	μ λ		
<b>№</b> P(3,M-3)	P(2,M-3)	P(1,M-3)		M-3
$3\mu$ $\lambda$	$2\mu$ $\lambda$	(μ λ)		
P(3,M-2)	P(2,M-2)	P(1,M-2)		M-2
$3\mu$ $\lambda$	$2\mu$ $\lambda_{2}$	μ λ		
VP(3,M-1)	P(2,M-1)	P(1,M-1)		M-1
$3\mu$ $\lambda$	$(2\mu \lambda)$	λ		
Y(3,M)	P(2,M)			M
$3\mu$ $\lambda$	$\left(\begin{array}{cc} 2\mu & \lambda \end{array}\right)$			
P(3,M+1)	P(2,M+1)			M+1
$(3\mu \lambda)$	$2\mu$ $\lambda_{\downarrow}$			
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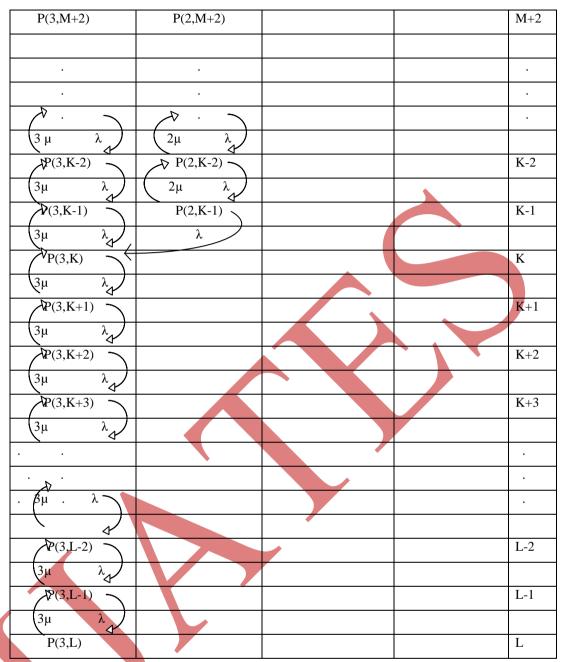


Fig. 1. State-transition-rate diagram for the controllable M/M/3 queueing system with finite capacity L operating under the tetrad {0...(Q.,R), N, M, K} policy

### **2.5 STEADY – STATE EQUATIONS:**

The transition-state diagram for the steady state problem of the controllable M/M/3 system with finite capacity and three removable servers under the tetrad {0, (Q, R), N, M, K} policy is shown in Fig. 1. The steady state probabilities equations governing the model are obtained as follows:

$$\lambda P(0,0) = \mu P(1,1)$$
 (1)

$$\lambda P(0,n) = \lambda P(0,n-1), \qquad 1 \le n \le N-1$$
 (2)

$$(\lambda + \mu)P(1,1) = \mu P(1,2)$$
 (3)

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.02, Issue No. 11, November 2014 ISSN (online): 2348 – 7550

$$(\lambda + \mu)P(1,n) = \lambda P(1,n-1) + \mu P(1,n+1) \qquad 2 \le n \le Q-1$$
 (4)

$$(\lambda + \mu)P(1,Q) = \lambda P(1,Q-1) + \mu P(1,Q+1) + 2\mu P(2,Q+1)$$
(5)

$$(\lambda + \mu)P(1,n) = \lambda P(1,n-1) + \mu P(1,n+1) \qquad \qquad Q+1 \leq n \leq N-1 \tag{6}$$

$$(\lambda + \mu)P(1, N) = \lambda P(1, N - 1) + \mu P(1, N + 1) + \lambda P(0, N - 1)$$
(7)

$$(\lambda + \mu)P(1,n) = \lambda P(1,n-1) + \mu P(1,n+1), \qquad N+1 \le n \le M-2 \tag{8}$$

$$(\lambda + \mu)P(1, M - 1) = \lambda P(1, M - 2)$$
(9)

$$(\lambda + 2\mu)P(2, Q + 1) = 2\mu P(2, Q + 2)$$
(10)

$$(\lambda + 2\mu)P(2, n) = \lambda P(2, n - 1) + 2\mu P(2, n + 1)$$
  $Q + 2 \le n \le R - 1$  (11)

$$(\lambda + 2\mu)P(2,R) = \lambda P(2,R-1) + 2\mu P(2,R+1) + 3\mu P(3,R+1)$$
(12)

$$(\lambda + 2\mu)P(2, n) = \lambda P(2, n - 1) + 2\mu P(2, n + 1) \qquad R + 1 \le n \le M - 1$$
(13)

$$(\lambda + 2\mu)P(2, M) = \lambda P(2, M - 1) + 2\mu P(2, M + 1) + \lambda P(1, M - 1)$$
(14)

$$(\lambda + 2\mu)P(2, n) = \lambda P(2, n - 1) + 2\mu P(2, n + 1) \qquad M + 1 \le n \le K - 2$$
(15)

$$(\lambda + 2\mu)P(2, K - 1) = \lambda P(2, K - 2)$$
 (16)

$$(\lambda + 3\mu)P(3, R + 1) = 3\mu P(3, R + 2)$$
(17)

$$(\lambda + 3\mu)P(3,n) = \lambda P(3,n-1) + 3\mu P(3,n+1) \qquad R+2 \le n \le K-1$$
(18)

$$(\lambda + 3\mu)P(3, K) = \lambda P(3, K - 1) + 3\mu P(3, K + 1) + \lambda P(2, K - 1)$$
(19)

$$(\lambda + 3\mu)P(3,n) = \lambda P(3,n-1) + 3\mu P(2,n+1) \qquad K+1 \le n L-1$$
 (20)

$$\lambda P(3, L-1) = 3\mu P(3, L)$$
 (21)

Equations (1)–(21) can be solved by using recursive method for the P(i,n) (i = 0, 1, 2, 3)

$$P(0,n) = P(0,0), \qquad 1 \le n \le N-1$$
 (22)

$$P(1_n, n) = \frac{\rho(1 - \rho^n)}{(1 - \rho)} P(0|0), \quad 1 \le n \le Q$$
 (23)

$$P(1,n) = \frac{\rho(1-\rho^n)}{(1-\rho)} + \frac{\rho(\rho^M - \rho^{M-N})(1-\rho^{n-Q})}{(1-\rho)(1-\rho^{M-Q})} P(0,0) \qquad Q+1 \le n \le N$$
(24)

$$P(1,n) = \left[\frac{\rho(1-\rho^{(1)})(\rho^{n-N}-\rho^{M-N})}{(1-\rho)(1-\rho^{M-Q})}\right]P(0,0), \qquad N+1 \le n \le M-1$$
 (25)

$$P(2,n) = \frac{\rho^{M-N-1}(1-\rho^N)\left[1-\frac{(\rho)}{2}\right]^{n-Q}}{(2-\rho)(1-\rho^{M-Q})}P(0,0), \qquad Q+1 \le n \le M$$
 (26)

$$P(2,n) = \frac{\rho^{M-N-1}(1-\rho^N)\left(\frac{\rho}{2}\right)^{n-M}\left[1-\left(\frac{\rho}{2}\right)^{M-Q}\right]}{(2-\rho)(1-\rho^{M-Q})} P(0,0), \quad M+1 \le n \le M \tag{27}$$

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.02, Issue No. 11, November 2014 ISSN (online): 2348 – 7550

$$P(3,n) = \frac{\rho^{K-M-1}(1-\rho^{M})\left[1-\left(\frac{\rho}{3}\right)^{n-R}\right]}{(3-\rho)(1-\rho^{K-R})}P(0,0), \qquad R+1 \le n \le K$$
(28)

$$P(3,n) = \frac{\rho^{K-M-1}(1-\rho^M)(\frac{\rho}{3})^{n-K}\left[1-\left(\frac{\rho}{3}\right)^{K-R}\right]P(0,0)}{(3-\rho)\left(1-\rho^{K-R}\right)}, \quad K+1 \le n \le L \tag{29}$$

Where 
$$\rho = \frac{\lambda}{\mu}$$

#### 3. THE GENERATING FUNCTIONS

The Generating function techniques applied to obtain analytic solutions P(i,n) (i = 0,1,2,3) in closed form expressions.

Partial probability generating functions are as follows:

$$F_0(z) = \sum_{n=0}^{N-1} z^n P(0,n), \quad |z| \le 1$$

$$F_1(z) = \sum_{n=1}^{M-1} z^n P(1, n), \quad |z| \le 1$$

$$F_2(z) = \sum_{n=Q+1}^{K-1} z^n P(2, n), \quad |z| \le 1$$

$$F_3(z) = \sum_{n=R+1}^{L} z^n P(3,n), |z| \le 1$$

### 4. PERFORMANCE CHARACTERISTICS OF THE SYSTEM:

In this section we obtain some performance characteristics using generating functions derived in previous section.

### EXPRESSIONS OF P<sub>0</sub>, P<sub>1</sub>, P<sub>2</sub> AND P<sub>3</sub>

$$P_0 = F_0(1) = \sum_{n=0}^{N-1} P(0, n),$$

$$P_1 = F_1(1) = \sum_{n=1}^{M-1} P(1, n),$$

$$P_2 = F_2(1) = \sum_{n=Q+1}^{K-1} P(2,n),$$

$$P_3 = F_3(1) = \sum_{n=R+1}^{L} P(3,n),$$

### THE EXPRESSIONS ARE L<sub>0</sub>, L<sub>1</sub>, L<sub>2</sub>, L<sub>3</sub> AND L<sub>S</sub>

$$\begin{split} L_0 &= \sum_{n=1}^{N-1} n P(0,n), \\ L_1 &= \sum_{n=1}^{M-1} n P(1,n), \\ L_2 &= \sum_{n=Q+1}^{K-1} n P(2,n), \\ L_3 &= \sum_{n=Q+1}^{L} n P(3,n), \end{split}$$

$$L_0 = [F_0'(z)]_{z=1} = \frac{N(N-1)}{2} P(0,0)$$
(30)

Similarly, we can find  $L_1$  we calculate  $[F_1(z)]_{z=1}$  using L'Hospital's rule twice to obtain

$$L_{1} = \frac{N\rho(1+\rho+N-N\rho)P(0,0) + \rho(M+1)(M\rho-M-2\rho)P(1,M-1)}{2(1-\rho)^{2}} - \frac{(0+1)(Q\rho-Q-2\rho)P(2,Q+1)}{(1-\rho)^{2}}$$
(31)

similarly

$$= \frac{(Q+1)(Q\phi - 2Q - 2\rho)P(2,Q+1) + \rho(K+1)(K\rho - K - 2\rho)P(2,K-1)}{(2-\rho)^2} - \frac{(R+1)(R\rho - R - 3\rho)P(3,R+1)}{2(2-\rho)^2}$$
(32)

$$L_{3} = \frac{(R+1)(R\rho - 3R - 2\rho)P(3, R+1) - \rho(3L+3 - L\rho)P(3, L)}{(3-\rho)^{2}} - \frac{\rho(K+1)(K\rho - 3K - 3\rho)P(2, K-1) - P(M+1)(M\rho - 2M - 2\rho)P(1, M-1)}{3(3-\rho)^{2}}$$
(33)

Hence we can easily obtain the expected number of customers in the system from (30)-(33)

\
$$L_s = L_0 + L_1 + L_2 + L_3$$
 (34)

#### 5. EXPECTED TOTAL COST FUNCTION

In this section we calculate the total expected cost function per unit time for the controllable  $M\M$  queueing system with finite capacity L operating under the tetrad  $\{0, (Q, R), N, M, K\}$  policy, in which  $\{0, (Q, R), N, M, K\}$  are decision variables. Along with our objective to determine the optimum value of the control parameters  $\{(Q,R), N, M, K\}$  say  $(Q^*, R^*, N^*, M^*, K^*)$ , so as to minimize the cost function, we also constructed the cost structure.

The total expected cost function per unit time is given by

Expected cost, F{(Q,R), N, M, K}

$$= C_h L_s + (C_{V1} + C_{V2} + C_{V3}) \frac{E[I]}{E[c]} + C_{01} \frac{E[B_1]}{E[C]} + C_{02} \frac{E[B_2]}{E[C]} + C_{03} + C_{04}$$

$$+ \lambda C_l P(3, l)$$
(35)

As the total expected cost function is highly non linear and complex, it is extremely difficult to determine the optimal values  $(Q^*, R^*, N^*, M^*, K^*)$ , analytically which minimize the total expected cost function per unit time. Direct search method may use to obtain useful results. In Direct search algorithm, it is compulsory to have upper bounds for decision variables and direct search algorithm can be terminated after obtaining a global optimum in the interior region. Here L is the upper bounds of the decision variables  $\{Q^*, R^*, N^*, M^*, K^*\}$ . Following are the steps in the direct search algorithm.

5.1 Find the optimal values ( $\mathbb{R}^*, N^*, M^*, K^*$ ) for fixed Q ie.

$$\min_{Q < N < M < K \le L-1} F(Q, R, N, M, K) = F(Q^*, R^*, N^*, M^*, K^*).$$

5.2 Find the set of all minimum cost solutions for Q = 1, 2, ... L-4 ie

$$\Phi = \{ F(Q, M^*, N^*, M^*, K^*) : Q = 1, 2, ... L - 4 \}$$

5.3 Find the optimal value  $Q^*$ , ie.

$$\min_{Q} \varphi \neq F(Q^*, R^*, N^*, M^*, K^*).$$

The computer software MATLAB is used for computer programming. Let the system capacity is L=20 & the fixed cost for every lost customer  $C_1=\$50$ .

Now, we use sensitivity analysis on the optimum value based on changes in specific values of the system parameters  $\lambda$  and  $\mu$ . The following cost elements are used:

Case I: 
$$C_h = \$10$$
,  $C_{01} = \$10$ ,  $C_{02} = \$20$ ,  $C_{03} = \$30$ ,  $C_v = C_{v1} + C_{v2} + C_{v3} = \$30$   
Case II:  $C_h = \$15$ ,  $C_{01} = \$10$ ,  $C_{02} = \$20$ ,  $C_{03} = \$30$ ,  $C_v = C_{v1} + C_{v2} + C_{v3} = \$30$   
Case III:  $C_h = \$10$ ,  $C_{01} = \$15$ ,  $C_{02} = \$30$ ,  $C_{03} = \$45$ ,  $C_v = C_{v1} + C_{v2} + C_{v3} = \$30$   
Case IV:  $C_h = \$10$ ,  $C_{01} = \$10$ ,  $C_{02} = \$20$ ,  $C_{03} = \$30$ ,  $C_v = C_{v1} + C_{v2} + C_{v3} = \$45$   
Case V:  $C_h = \$10$ ,  $C_{01} = \$10$ ,  $C_{02} = \$20$ ,  $C_{03} = \$30$ ,  $C_v = C_{v1} + C_{v2} + C_{v3} = \$30$ 

Applying the Direct search algorithm the optimal value of

(Q, R, N, M, K),  $(Q^*, R^*, N^*, M^*, K^*)$  and its minimum expected cost  $F(Q^*, R^*, N^*, M^*, K^*)$ .

for the above five cases are shown in Table A and Table B for various values of  $(\lambda, \mu)$ .

### (For fixed value of $\lambda=4$ )

The Expected cost  $F(Q^*, R^*, N^*, M^*, K^*)$  and the optimal value  $(Q^*, R^*, N^*, M^*, K^*)$ 

	(λ,μ)	(4,5)	(4,6)	(4,7)	(4,8)	(4,9)	(4,10)
G. T.	(0° D° N° M° K°)	(2.2.4.7.6)	(0.45.65)	(0.45.65)	(2.45.65)	(2.4.5.6.0)	(4.5.6.5.0)
Case I	$(Q^{\bullet}, R^{\bullet}, N^{\bullet}, M^{\bullet}, K^{\bullet})$	(2,3,4,5,6)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,8)	(4,5,6,7,8)
	$F(Q^*, R^*, N^*, M^*, K^*)$	99.57	101.23	103.31	105.14	106.12	107.59
Case II	$(Q^*,R^*,N^*,M^*,K^*)$	(1,2,3,4,5)	(1,2,3,4,5)	(1,2,3,4,5)	(2,3,4,5,6)	(2,3,4,5,6)	(2,3,4,5,6)
	$F(Q^*, R^*, N^*, M^*, K^*)$	144.21	146.35	149.73	151.64	153.81	155.60
Case III	$(Q^*,R^*,N^*,M^*,K^*)$	(2,3,4,5,6)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,8)	(4,5,6,7,8)
	$F(Q^*, R^*, N^*, M^*, K^*)$	107.67	108.22	110.34	112.26	113,49	114.73
Case IV	$(Q^*,R^*,N^*,M^*,K^*)$	(2,3,4,5,6)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,8)	(3,4,5,6,9)	(4,5,6,7,8)
	$F(Q^*, R^*, N^*, M^*, K^*)$	104.52	107.21	111.32	114.69	117.74	120.54
Case V	$(Q^*,R^*,N^*,M^*,K^*)$	(4,5,6,7,8)	(5,6,7,8,9)	(5,6,7,8,9)	(6,7,8,9,10)	(6,7,8,9,10)	(6,7,8,9,10)
	$F(Q^*, R^*, N^*, M^*, K^*)$	126.52	132.43	137.35	142.61	151.78	153.67

Through the analysis of *Table A*, we observed that

- (a)  $F(Q^*, R^*, N^*, M^*, K^*)$  increases as  $\mu$  increases in all the cases.
- (b)  $(Q^*, R^*, N^*, M^*, K^*)$  slightly changes as  $\mu$  increases.
- (c)  $(Q^*, R^*, N^*, M^*, K^*)$  decreases as  $C_h$  increases.
- (d)  $(Q^*, R^*, M^*, K^*)$  are almost the same for case 1, case 3, case 4 intuitively.  $C_{01}$ ,  $C_{02}$ ,

 $C_{03}$  and  $C_v$  rarely affect the optimal values of (Q, R, N, M, K)

### (For fixed value of $\mu$ =7)

The Expected cost  $F(Q^*, R^*, N^*, M^*, K^*)$  and the optimal value  $(Q^*, R^*, N^*, M^*, K^*)$ 

	(λ,μ)	(1,7)	(2,7)	(3,7)	(4,7)	(5,7)	(6,7)
Case I	$(Q^*, R^*, N^*, M^*, K^*)$	(2,3,4,5,6)	(2,3,4,5,6)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)
	$F(Q^*, R^*, N^*, M^*, K^*)$	74.62	96.51	97.64	101.23	103.52	105.34
Case II	$(Q^*,R^*,N^*,M^*,K^*)$	(1,2,3,4,5)	(2,3,4,5,6)	(2,3,4,5,6)	(2,3,4,5,6)	(2,3,4,5,6)	(2,3,4,5,6)
	$F(Q^*, R^*, N^*, M^*, K^*)$	101.67	124.79	136.81	142.90	151.87	156.92
CaseIII	$(Q^*,R^*,N^*,M^*,K^*)$	(2,3,4,5,6)	(2,3,4,5,6)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)
	$F(Q^{\circ}, R^{\circ}, N^{\circ}, M^{\circ}, K^{\circ})$	82.62	94.23	104.34	112.11	117.83	123.97
Case IV	$(Q^*,R^*,N^*,M^*,K^*)$	(2,3,4,5,7)	(2,3,4,5,7)	(2,3,4,5,8)	(3,4,5,6,7)	(3,4,5,6,7)	(3,4,5,6,7)
	$F(Q^*, R^*, N^*, M^*, K^*)$	93.73	102.69	108.09	110.21	112.34	114.34

International Journal of Advanced Technology in Engineering and Science www.ijates.com Volume No.02, Issue No. 11, November 2014 ISSN (online): 2348 – 7550

Case V	$(Q^*,R^*,N^*,M^*,K^*)$	(3,4,5,6,8)	(4,5,6,7,8)	(5,6,7,8,9)	(5,6,7,8,9)	(5,6,7,8,9)	(4,5,6,7,8)
	$F(Q^*, R^*, N^*, M^*, K^*)$	106.58	126.83	134.09	136.11	138.34	139.31

Through the analysis of *Table B*, we observed that

- (e)  $F(Q^*, R^*, N^*, M^*, K^*)$  increases as  $\lambda$  increases in all the cases.
- (f)  $(Q^*, R^*, N^*, M^*, K^*)$  slightly changes as  $\lambda$  increases.
- (g)  $(Q^*, R^*, N^*, M^*, K^*)$  decreases as  $C_h$  increases.
- (h)  $(Q^*, R^*, N^*, M^*, K^*)$  are almost the same for case 1, case 3, case 4 intuitively.  $C_{01}$ ,  $C_{02}$ ,  $C_{03}$  and  $C_v$  rarely affect the optimal values of (Q, R, N, M, K).

### 6. CONCLUSIONS:

In this paper we derived the analytic steady-state results for the controllable  $M\backslash M\backslash 3$  queueing system with finite capacity operating under the tetrad(0, Q, R, N, M, K) policy. Sensitivity analysis between the optimal value of (Q, R, N, M, K) and the specific values of  $\lambda$  and  $\mu$  and the cost elements  $C_h$ ,  $C_{01}$ ,  $C_{02}$ ,  $C_{03}$  and  $C_v$ . It is also noticed that  $C_{01}$ ,  $C_{02}$ ,  $C_{03}$  and  $C_v$  rarely affect the optimal values of (Q, R, N, M, K) and  $C_h$  affected the optimal values slightly. This paper is the generalization of the ordinary  $M\backslash M\backslash 2$  queueing system and the N-policy  $M\backslash M\backslash 1$  queueing system. Finally, a cost model is evaluated to determine the optimal level

 $(Q^*, R^*, N^*, M^*, K^*)$  of failed machines in the system.

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