CONTROLLING OF THEFT VEHICLES USING CAN

SUMANTH VIGNESH.P¹, RAGHAV.V², SAKTHIVEL.V³, KISHORE.M⁴, MOHAN RAJ⁵

^{1, 2, 3} UG Student, Dept. of Electronics and Communication Engineering, Bharath University, (India)

ABSTRACT

Dodging Vehicle Theft is making buzz in present auto industry. Outline and advancement of a robbery control framework for an auto, can be attained to by making utilization of GPS highlight of cellular telephone. The created framework makes utilization of a cell telephone that is installed in the vehicle with an interfacing to Engine Control Module (ECM) through Control Area Network (CAN) Bus, which is thus, conveyed to the ECM. The vehicle being stolen can be ceased by utilizing GPS highlight of cell telephone and this data is utilized by the holder of the vehicle for future handling. The holder sends the message to the versatile which is implanted in the vehicle which has stolen which thusly controls the vehicles motor by locking the working of the motor promptly. The created framework acknowledge the message and telecasted to the Vehicle Network through CAN Bus. The motor can be opened just by the manager of the vehicle by sending the message once more. The objective behind the outline is to create security for vehicles and inserted framework to speak with motor of the vehicle.

Keywords: Controller Area Network Bus, Engine Control Unit, Vehicle Network, Mobile Phone, GPS, GSM, Theft Control Unit

I. INTRODUCTION

Today's Automobiles, unendingly comply with cutting edge control systems as a result of relentless advancement in development. Late Vehicles contains far reaching number of Electronic Control Systems and starting now there are considerable amounts of Electronic Control Units present. The advancement of auto contraptions is the result social events of the customers wish for better wellbeing and more noticeable comfort besides for diverse necessities like upgraded release control and diminished fuel use.

Car industry uses Controller Area Network (CAN) as the in-vehicle framework for the Engine Management, the body devices like gateway and roof control, circulating air through and cooling and lighting furthermore for the incitement control. Nowadays all most all auto makers have moreover started executing CAN based vehicle automation. CAN frameworks used as a piece of engine organization to join a couple of ECUs.

II. PROPOSED SYSTEM

Industrially accessible against robbery vehicular frameworks are extremely extravagant. The paper demonstration towards with the configuration & advancement of a Theft Control System for a car, which is being utilized to avert or control the burglary of a vehicle. The created framework makes utilization of an implanted framework and n GSM/GPS innovation. The proposed framework, introduced in the vehicle can be

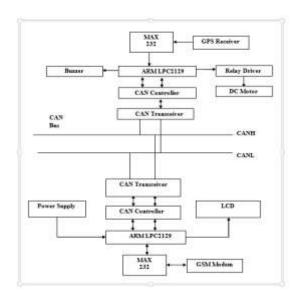
⁴ Asst. Professor, Dept. of Electronics and Communication Engineering, Bharath University, (India)

effortlessly controlled by the manager of the vehicle by communicating something specific from his/her portable to the vehicle motor by interfacing with CAN transport and GSM modem.

Once, the vehicle is being stolen, the data is being utilized by the vehicle holder for further preparing, where by sitting at a remote place, a message is sent to the interfacing GSM modem that is interfaced with the ECU which is introduced in the vehicle. By perusing the signs got by the versatile, the motor is bolted naturally and velocity of the vehicle lessened to zero. Again it will go to the typical condition when entering a secured secret word by the manager of the vehicle.

The primary thought behind the configuration is to bring the Mobile advancements into the installed framework. The outlined unit is exceptionally savvy. The whole outlined unit is on a solitary chip (ECU). At the point when the vehicle is stolen, holder will make an impression on the versatile which is installed in the auto demonstrating the definite area utilizing GPS. To stop the vehicle, manager makes an impression on control framework set in vehicle as an ECU that consequently stops the stream of the fuel in the vehicle by sending message Numerous present day vehicle GPS beacons join both dynamic and uninvolved following capacities. The proposed framework is exceptionally dependable, when a cell system is accessible and a following gadget is joined it transmits information to a server; when a system is not accessible the gadget stores information in inner memory and will transmit put away information to the server later when the system gets to be accessible once more.

Vehicle following has been achieved by introducing a container into the vehicle, either self-controlled with a battery or wired into the vehicle's energy framework. For nitty gritty vehicle spotting and following it is still the prevalent system however numerous organizations are progressively intrigued by the developing wireless advancements that give following of various substances, for example, both a businessperson and their vehicle alternatives.



III. WORKING OF THE PROPOSED SYSTEM

The primary thought behind the configuration is to bring the Mobile advancements into the installed framework. The outlined unit is exceptionally savvy. The whole outlined unit is on a solitary chip (ECU). At the point when the vehicle is stolen, holder will make an impression on the versatile which is installed in the auto demonstrating the definite area utilizing GPS. To stop the vehicle, manager makes an impression on control framework set in vehicle as an ECU that consequently stops the stream of the fuel in the vehicle by sending message Numerous present day vehicle GPS beacons join both dynamic and uninvolved following capacities. The proposed

framework is exceptionally dependable, when a cell system is accessible and a following gadget is joined it transmits information to a server; when a system is not accessible the gadget stores information in inner memory and will transmit put away information to the server later when the system gets to be accessible once more.

Vehicle following has been achieved by introducing a container into the vehicle, either self-controlled with a battery or wired into the vehicle's energy framework. For nitty gritty vehicle spotting and following it is still the prevalent system however numerous organizations are progressively intrigued by the developing wireless advancements that give following of various substances, for example, both a businessperson and their vehicle. These frameworks additionally offer following of calls, messages and Web utilization and by and large give a more extensive scope of alternatives.

IV. AREA RETRIEVAL OF THE VEHICLE

Area of the vehicle is a two way prepare. At first scope and longitude of the vehicle is to be gotten from the satellites. Gotten scope and longitude is utilized for further reckoning of geological address by conjuring goecoder. The manager can recover the area just after sending a lone message. This lone message is situated by the holder before conveying the framework. Recovery of the vehicle's area is clarified in the action graph demonstrated in Fig. 4

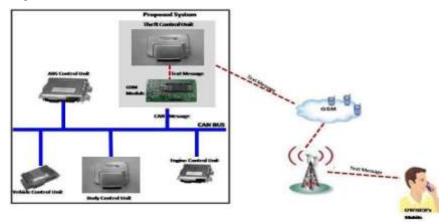


Fig. 3. Diagram of the Proposed System

Endless supply of relating message code, the application would begin the administration. As an affirmation, the manager is sent with scope, longitude and the land address. Portable system is a matter of concern as just in vicinity of significant system scope singular message and its receipt is conceivable. Outline of area recovery module looks into both the system variable and client code validation. Just after getting a validated code that has been characterized prior, the holder is sent the area.

4.1 Power Supply Unit

The supply of 5V DC is given to the framework which is changed over from 230V AC supply. Firstly, the venture down transformer will be utilized here for changing over the 230V AC into 12V AC. The microcontroller will bolster just the DC supply, so the AC supply will be changed over into DC utilizing the scaffold rectifier. The yield from the channel is given to the 7805 voltage controller which will change over the 12V DC into 5V DC, so the unadulterated 5V DC is getting as the yield from the force supply unit.

4.2 Microcontroller Unit

The microcontroller unit contain the two arm micro controller one is utilized for send and get the sms and an alternate arm microcontroller is utilized to get gps esteem and ON/OFF the buzzer,DC engine.

4.3 Display unit

The presentation unit is chiefly is predominantly accomplished by the 16X2 LCD. A fluid precious stone showcase (LCD) is a level board show, electronic visual presentation, or feature show that uses the light adjusting properties of fluid gems (LCs). LCs does not radiate light specifically. In this undertaking LCD is utilized to show sensor esteem

4.4 Communication Unit

In our undertaking GSM and CAN is the correspondence unit GSM is utilized to send and get the sms the CAN is utilized to make the correspondence between two controller.

4.5 Software Unit

Programming is utilized to assemble the coding of the coveted application for the relating installed framework.

V. KEIL PROGRAMMING

Keil Software is the main merchant for 8/16-bit improvement devices (positioned at first position in the 2004 Embedded Market Study of the Embedded Systems and EE Times magazine). Keil Software is spoken to worldwide in more than 40 nations. Since the business sector presentation in 1988, the Keil C51 Compiler is the true business standard and backings more than 500 current 8051 gadget variations. Presently, Keil Software offers improvement instruments for ARM.



Fig. 5. Block Diagram of The Engine Ignition Control Module

Upon receiving the message and verifying its authentication, the micro controller installed on the vehicle would send a signal to the relay to lock or unlock the engine. A SIM card on GSM module installed on the vehicle would receive the message and would forward it to the micro controller. A MAX232 would perform the action of both driver and receiver to forward the message to and from the micro controller as shown in Fig. 5.

An LCD display is used to notify the changes. Corresponding messages would be display on the LCD when a new message is received, when locking or starting the engine is performed. This kit however is not essential for actual deployment of the system and is used only for demonstration purpose.

5.1 Given Input Power Supply Unit

The supply of 5V DC is given to the framework which is changed over from 230V AC supply. Firstly, the venture down transformer will be utilized here for changing over the 230V AC into 12V AC. The microcontroller will bolster just the DC supply, so the AC supply will be changed over into DC utilizing the scaffold rectifier. The yield of the rectifier will have swells so we are utilizing the 2200uf capacitor for sifting those swells. The yield from the channel is given to the 7805 voltage controller which will change over the 12V

DC into 5V DC. The yield from the controller will be separated utilizing the 1000uf capacitor, so the unadulterated 5V DC is getting as the yield from the force supply unit. Here we are utilizing the PIC microcontroller which will be equipped for getting the supply of 5V DC so we need to change over the 230V AC supply into 5V DC supply

- Processor wake-up from Power-down mode through outside intrude.
- Individual empower/handicap of fringe capacities for force advancement.

VI. EXPERIMENTAL RESULTS

The outcomes are gotten in the wake of doing the experimentation by utilizing the accompanying equipment parts. The segment incorporates Android Based Phone, ARM Controller, Relay Circuit, GSM Module, and LCD Display.

Fig. 6 shows ARM Controller, Relay circuit, GSM Module and LCD Display are interfaced on a solitary board and inserted on single board which is installed to a vehicle as a control unit. The hand-off is joined with the Vehicle Engine Unit of the Automobile.



Fig. 6. Equipment Kit installed to the vehicle

At the point when "OFF" message sent by the manager of the vehicle to the portable implanted in the control unit, the controller shows the message in the LCD as demonstrated in Fig. 7(a) and summons the hand-off that is joined with the vehicle motor which will stop fuel stream consequently bolting the vehicle motor by sending message through the CAN Bus in the CAN comprehensible organization.

Likewise when "ON" message sent by the manager of the vehicle to the versatile installed in the control unit, the controller shows the message in the LCD as demonstrated in Fig. 7(b) and conjures the transfer that is associated with the vehicle motor which will thus permits the fuel stream by opening the vehicle motor by sending message through CAN Bus.

6.1 Double Power Supply

- CPU working voltage scope of 1.65V to 1.95V (1.8V +/ 8.3%).
- I/O power supply scope of 3.0V to 3.6V (3.3V + / -10%)

International Journal of Advanced Technology in Engineering and Science www.ijates.com

Volume No.03, Issue No. 04, April 2015

ISSN (online): 2348 – 7550

VII. APPLICATIONS

- Industrial control
- · Medical frameworks
- · Access control
- Point-of-offer
- Communication portal
- Embedded delicate modem
- General reason application

VIII. UARTOFEATURES

- 16 byte Receive and Transmit FIFOs.
- Register locations conform to '550 industry standard.
- Collector FIFO trigger focuses at 1, 4, 8, and 14 bytes.
- Built-in baud rate generator

UARTO Receiver Buffer Register (U0RBR - 0xE000C000 when DLAB = 0, Read Only)

The U0RBR is the upper byte of the UART0 Rx FIFO. The upper byte of the Rx FIFO contains the most seasoned character got and can be perused by means of the transport interface. The LSB (bit 0) speaks to the "most established" got information bit. On the off chance that the character got is under 8bits, the unused MSBs are cushioned with zeroes.

IX. I2C INTERFACE

9.1 Highlights

- Standard I2C consistent transport interface.
- Programmable clocks permit flexible rate control.
- Bidirectional information exchange in the middle of experts and slaves.
- Multi-expert transport (no focal expert).
- Arbitration between all the while transmitting bosses without debasement of serial information on the transport.
- Serial clock synchronization permits gadgets with diverse bit rates to convey through one serial transport.
- Serial clock synchronization can be utilized as a handshake instrument to suspend and resume serial exchange.
- The I2C transport may be utilized for test and demonstrative purposes.

9.2 APPLICATIONS

- Interfaces to outside I2C standard parts, for example, serial RAMs, LCDs, tone generators, and so forth.
- Data exchange from an expert transmitter to a slave recipient. The principal byte transmitted by the expert is the slave address. Next takes after various information bytes. The slave gives back a recognize bit after every got byte.
- Data exchange from a slave transmitter to an expert recipient. The main byte (the slave location) is transmitted by the expert. The slave then returns a recognize bit. Next takes after the information bytes transmitted by the slave to the expert.

International Journal of Advanced Technology in Engineering and Science www.ijates.com

Volume No.03, Issue No. 04, April 2015

Hinder 1: MAX232

It is utilized to change over the voltage level when we speak the information with the microcontroller and PC. Here the message will be transmitted to the checking segment by method for GSM modem. To give the information to the GSM modem we are striving for the max232. In this venture the position of the robot, the discovery of the breaks will be send as the message to the observing segment.

ISSN (online): 2348 – 7550

Hinder 2: GPS

The Global Positioning System (GPS) is a space-based satellite route framework that gives area and time data in all climate, anyplace on or close to the Earth, where there is an unhampered viewable pathway to four or more GPS satellites. It is kept up by the United States government and is openly available to anybody with a GPS collector.

Hinder 3: DC engine

A DC engine is intended to run on DC electric force. Two samples of unadulterated DC plans are Michael Faraday's homopolar engine (which is unprecedented), and the metal ring engine, which is (in this way) an oddity. By a wide edge the most extraordinary DC motor sorts are the brushed and brushless sorts, which utilize inside and outside recompense individually to make a wavering AC current from the DC source— so they are not simply DC machines in a strict sense.

Hinder 4: BUZZER

Ringers like the TMB-arrangement are attractive capable of being heard sign gadgets with implicit wavering circuits. The development joins a wavering circuit unit with an area twist, a drive circle and appealing transducer .Transistors, resistors, diodes and other little gadgets go about as circuit gadgets for driving sound generators. With the usage of voltage, current streams to the drive circle on vital side and to the distinguishment twist on the discretionary side.

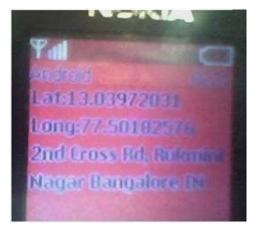
Hinder 5: LCD

A fluid gem show (LCD) is a level board show, electronic visual showcase, or feature show that uses the light balancing properties of fluid precious stones (LCs). LCs does not transmit lightdirectly.LCD is utilized to show the consequences of the framework operation, for example, sensed qualities, engine status and etc.......

X. FUTURE ENHANCEMENT

The future improvement can be conveyed on any vehicles, less extravagant and ignition of a motor can be controlled being at the remote spot, incorporates a few points of interest of the framework. Thusly, the Mobile based Vehicle Theft control Unit (TCU) gives a simpler and emphasized following framework. Likewise helps the manager of the vehicle to have a simple remote control of the robbery vehicle.

The Fig. 9 shows the typical message sent by the Android mobile to the owner mobile when there is a network, by invoking Vanet app in Android mobile and hence displaying the location in terms of latitude, longitude and geo-graphical address of the location.



XI. CONCLUSION

In the current framework the manual work is required thus we strive for our proposed framework. In our proposed framework we are going to make can controlled car.

REFERENCES

- [1] AmbadeShrutiDinkar and S.A Shaikh," Design and Implementation Of Vehicle Tracking System Using GPS", Journal of Information Engineering and Applications, ISSN 2224-5758, Vol 1, No.3, 2011. [2]CAN in Automation (CiA), Controller Area Network (CAN). Available: http://www.can-cia.org/
- [3] Daniel Switkin, "Android Application Devlopment",2010.
- [4] Feng Huang, Shanyu Tang, Senior Member, IEEE, and Jian Yuan, "Vehicle Location Based System", IEEE June, Transactions on no information forensics and security, vol.6, 2, 2011. [5] GPSImages[online:] www.gpsvehiclenavigation.com/GPS/images.p.
- [6] HuaqunGuo,JunJieAng and Yongdong Wu, "Extracting Controller Area Network Data for Reliable Car Communications", I Proc. IEEE,2009,pp.1027-1032.
- [7] HuaqunGuo,LekHengNgoh,YongdongWu,LianHwaHiow,ChoonHweeKwek,Feng Tao and Jun JieAng, " Embedded Info-Security Solutions for Vehicular Network", I Proc. CHINACOM'08, Hanghzhon, China, August 25-27,2008.
- [8] Jing Xu, TaoLu, Lingling Gao, "Design and Application of In-Vehicle Terminal for Car Network System Based on ARM9", IEEE International Workshop on Education Technology and Training, 2008, p.324-327.
- [9] K Punitha, S Arun Kumar and n Vijay Ganesh, "Control Area neywork for Reliable Car Communication", I Proc. International Journal of Computer Application(ICVCI),34-38,2011.
- [10] LI Gangyan,Xu Jun, "An Information Acquisition Method of City Bus Integrated Control Network", IEEE Computer Society,2008,722-725. [11]Robert Bosch Gmbh Controller Area Network (CAN). Avaliable: http://www.semiconductor.bosch/en/20/can/indexx/asp [12]R. Parsad, M. Ruggieri (2005) Applied Satellite Navigation Using GPS, GALILEO, and Augmentation Systems,London, ARTECH HOUSE.
- [11] "Real Time Web based Vehicle Tracking using GPS", World Academy of Science, Engineering and Technology 2010 Ph.D. Associate Professor College of Computer and Information Sciences Prince Sultan University.