

# DETECTION OF BLACK HOLE ATTACK IN VANET

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## ABSTRACT

*In the black hole attack, the attacker node that wants to interrupt node packets utilizes the routing protocol to establish the false fact that it has shortest path to the node. This is termed as black hole attack. When the malicious nodes are present between the communicating nodes, it performs any sort of action with those packets that crosses them. Users require safety on road in vehicular network and it could be possible by implementing VANET applications. Vehicular applications must be secured; if attackers change the content of safety applications then users are directly affected. Attackers change their attacking behavior and they launch different attacks at different time. In this thesis, we can identify attacks and understand attackers by using the classes of attack. We will develop such system to identify attacks in network with respect to some specific class of attack. If we control attackers and their attacks then it would help in saving human life. Also, an effective solution is proposed for DOS based attack (Black hole attack) which use the redundancy elimination mechanism consists of rate decreasing algorithm and state transition mechanism as its components.*

**Keywords:** *Black Hole Attack, VANET*

## I. INTRODUCTION

Attackers can be classified according to scope, nature, and behavior of attacks [15,16]. Some types of attackers are discussed:

- i. Some attackers eavesdrop only on the wireless channel to collect traffic information which maybe passed onto other attackers. As these attackers do not participate in the communication process of the network, they are called passive attackers. On the other hand, some attackers either generate packets containing wrong information or do not forward the received packets. These are called active attackers.
- ii. Attacker may be an authentic member of a VANET having authentic public keys and access to other members of the network. Such attackers are called insider. Outside attackers (outsider) are intruders and they can launch attacks of less diversity .
- iii. Some attackers are not personally benefited from the attack. Their aim is to harm other members of the network or disrupt the functionality of a VANET. These attackers are malicious. On the other hand, rational attacker seeks personal benefit and is more predictable in terms of type and target of the attack.
- iv. Local attacker launches an attack with a limited scope, that is, an attack is restricted to a particular area.

An attack can be extended, where an attacker can control several entities distributed across the network.

VANET is a special type of MANET, in which vehicles act as nodes. Unlike MANET, vehicles move on predefined roads, vehicles velocity depends on the speed signs and in addition these vehicles also have to follow

traffic signs and traffic signals [5]. There are many challenges in VANET that are needed to be solved in order to provide reliable services. Stable & reliable routing in VANET is one of the major issues. Hence more research is needed to be conducted in order to make VANET more applicable. As vehicles have dynamic behavior, high speed and mobility that make routing even more challenging.

## II. CLASSES OF ATTACK

### i. Class A

Even if there are advances in VANET but still it has many challenges to be overcome. This challenge is attacks on VANET. Raya et al. [34] classifies attacker as having three dimensions: “insider versus outsider”, “malicious versus rational”, and “active versus passive”. Before designing any security solution for VANETs [35, 36], we should firstly know different types of security threats or attacks. There are different classes of attacks:

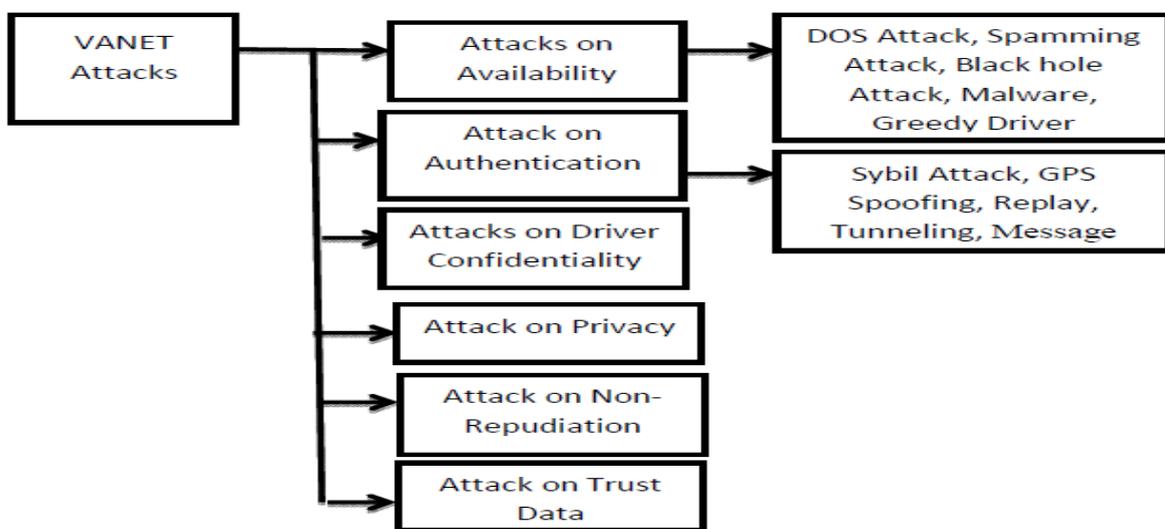


Figure 1: Type of attack

### i. Class A : Attack on Availability

1. In basic level the attacker overwhelm the node resource so that it cannot perform other necessary tasks which results in becoming the node continuously busy and not able to do anything else.
2. In extended level the attacker jam the channel by generating the high frequency in the channel so no vehicle is able to communicate to other vehicle in the network.
3. Drop the packets.

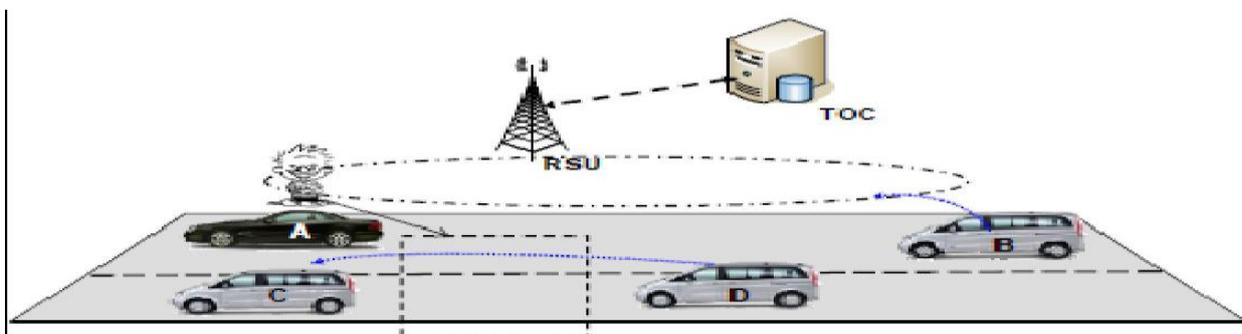


Figure 2

## ii. Class B: Attacks on Authentication

- It is a critical attack. In this attack an attacker pretends to have multiple identities [41]. An attacker transmits multiple messages with different ids to the other vehicles. In this way other vehicles feel that these messages are coming from different vehicles, so there is a jam further and they are enforced to take alternate route [42]. In other words we can say that the main task of the attacker is to provide an illusion of multiple vehicles to other vehicles and to enforce them to choose alternate route and leave the road for the benefits of the attacker. This task is done by sending multiple messages with different ids.

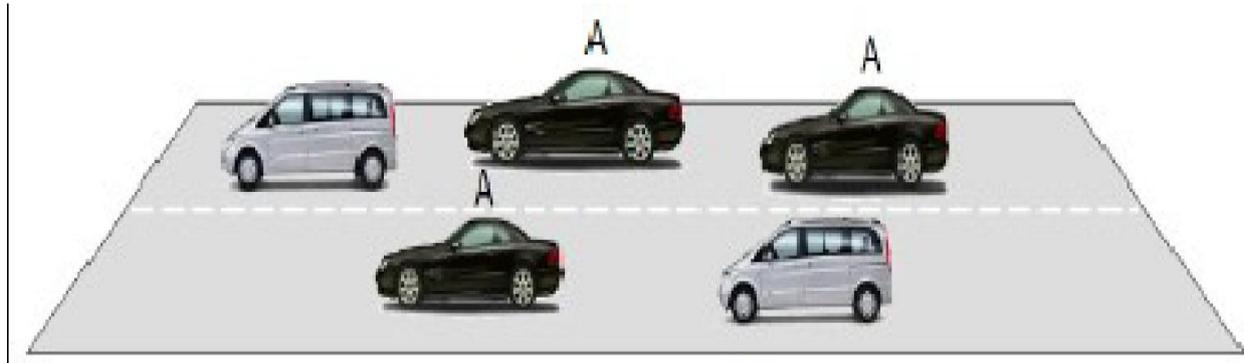


Figure 3

## iii. Class C: Attacks on Driver Confidentiality

Confidentiality of messages exchanged between the users of a typical VANET is vulnerable with malicious techniques such as eavesdropping and also collecting location information available through the broadcast messages. In the case of eavesdropping, attacker can collect information about exist users without their permission and use the information at a time. Location privacy and anonymity are important issues for vehicle users. Location privacy involves protecting users by obscuring the user's exact location in space and time [47]. By concealing a user's request so that it is indistinguishable from other users' requests, a degree of anonymity can be achieved.

## iv. Class D: Attack on Privacy

This type of attack is related with unauthorized accessing important information about vehicles. There is direct relation between driver and vehicle. If the attackers illegally access some data this directly affect the driver's privacy [44]. Usually a vehicle owner is also its driver, so if an attacker is getting the owner's identity then indirectly vehicle could put its privacy at risk; this type of privacy attack is called as identity revealing. Location tracking is also one of the well known privacy attacks. In this attack the location of vehicle or the path followed by that vehicle at particular period of time is considered as a personal data.

## v. Class E: Attack on Non-Repudiation

When two or more user shares the same key then non-repudiation [48] is occurred. Due to this, two users are not distinguished from each other and hence their actions can be repudiated. An identical key in different vehicle should be avoided using a reliable storage.

## vi. Class F: Attack on Data Trust

Data trust can be compromised by simply inaccurate data calculation and sending affected message, this can be done by manipulating sensors in vehicle, or by changing the sent information [44]. This affects the whole

system reliability. And hence some mechanisms must be developed to protect against such attacks in practice in vehicular network.

### III. DESCRIPTION OF BLACK HOLE ATTACK

Security is the major issue in VANET. Majority of the attacks were against Physical, MAC and few more layers which deals with routing mechanism of Vehicular ad hoc network. Primarily the attacks were classified based on the purpose (i.e) not forwarding the packets through routing mechanism, which affects sequence number and hop count. In the Black Hole attack malicious vehicle waits for the neighbors' to initiate a RREQ packet. Since the receivable RREQ Packet reaches the vehicle, it will immediately send a false RREP packet with a modified higher sequence number. A malicious vehicle where there is a possibility of Black hole attack which submerge all data packets of all objects and the packet will not be distributed further. The AODV protocol is vulnerable to such kind of attack because of having network centric property, where each vehicle of the network has to shares their routing tables among each other. Black Hole attack involves some modification of the data stream or the creation of a false stream

[6]. Figure 1 below show a simple scenario of this attack with one malicious vehicle.

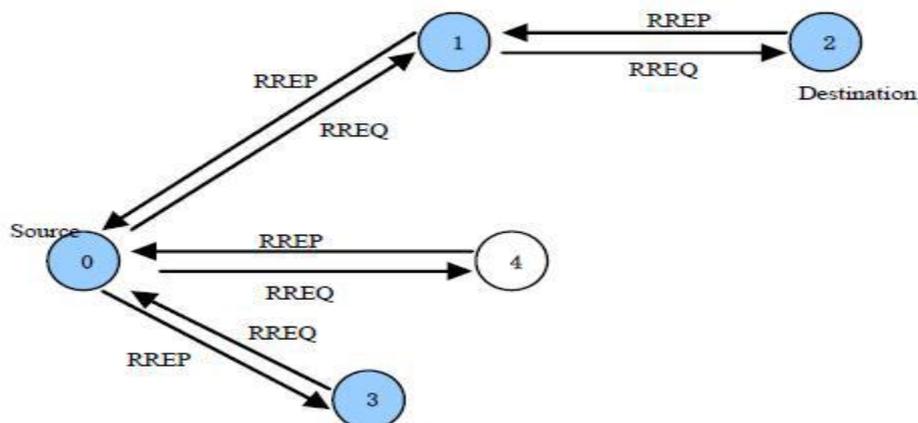


Figure 4

The AODV protocol is vulnerable to the well-known black hole attack. AODV uses sequencenumbers to determine the freshness of routing information and to guarantee loop-free routes. In case of multiple routes, a vehicle selects the route with the highest sequence number. If multiple routes have the same sequence number, then the vehicle chooses the route with the shortest hop count. A malicious vehicle sends Route Reply (RREP) messages without checking its routing table for a fresh route to a destination. As shown in Figure 1 above, source vehicle 0 broadcasts a Route Request (RREQ) message to discover a route for sending packets to destination vehicle 2. A RREQ broadcast from vehicle 0 is received by neighboring vehicles 1, 3 and 4. However, malicious vehicle 4 sends a RREP message immediately without even having a route to destination vehicle 2. A RREP message from a malicious vehicle is the first to arrive at a source vehicle. Hence, a source vehicle updates its routing table for the new route to the particular destination vehicle and discards any RREP message from other neighboring vehicles even from an actual destination vehicle. Once a source vehicle saves a route, it starts sending buffered data packets to a malicious vehicle hoping they will be forwarded to a destination vehicle. Nevertheless, a malicious vehicle (performing a black hole attack) drops all data packets rather than forwarding them on.

#### IV. NS2 INTRODUCTION

Network Simulator (Version 2), widely known as NS2, is simply an event driven simulation tool that has proved useful in studying the dynamic nature of communication networks. Simulation of wired as well as wireless network functions and protocols (e.g., routing algorithms, TCP, UDP) can be done using NS2. In general, NS2 provides users with a way of specifying such network protocols and simulating their corresponding behaviors. Due to its flexibility and modular nature, NS2 has gained constant popularity in the networking research community since its birth in 1989. Ever since, several revolutions and revisions have marked the growing maturity of the tool, thanks to substantial contributions from the players in the field. Among these are the University of California and Cornell University who developed the REAL network simulator the foundation which NS is based on. Since 1995 the Defense Advanced Research Projects Agency (DARPA) supported development of NS through the Virtual Inter Network Test bed (VINT) project [49]. Currently the National Science Foundation (NSF) has joined the ride in development. Last but not the least, the group of researchers and developers in the community are constantly working to keep NS2 strong and versatile. NS2 provides users with executable command ns which takes on input argument, the name of a Tcl simulation scripting file. Users are feeding the name of a Tcl simulation script (which sets up a simulation) as an input argument of an NS2 executable command ns. In most cases, a simulation trace file is created, and is used to plot graph and/or to create animation. NS2 consists of two key languages: C++ and Object-oriented Tool Command Language (OTcl). While the C++ defines the internal mechanism (i.e., a backend) of the simulation objects, the OTcl sets up simulation by assembling and configuring the objects as well as scheduling discrete events (i.e., a front end). The C++ and the OTcl are linked together using TclCL. Mapped to a C++ object, variables in the OTcl domains are sometimes referred to as handles. Conceptually, a handle (e.g., n as a Node handle) is just a string (e.g.,\_o10) in the OTcl domain, and does not contain any functionality. Instead, the functionality (e.g., receiving a packet) is defined in the mapped C++ object (e.g., of class Connector). In the OTcl domain, a handle acts as a frontend which interacts with users and other OTcl objects? It may define its own procedures and variables to facilitate the interaction. Note that the member procedures and variables in the OTcl domain are called instance procedures and instance variables (instvars), respectively. Before proceeding further, the readers are encouraged to learn C++ and OTcl languages.

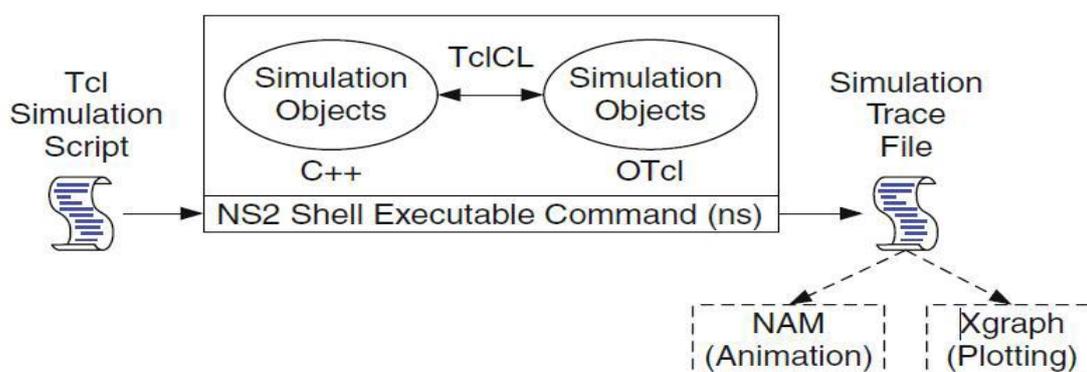


Figure 5

## V. RESULT AND FUTURE SCOPE

Vehicular Ad hoc Networks is a special kind of mobile ad hoc network to provide communication among nearby vehicles and between vehicles and nearby fixed equipments. VANETs are mainly used for improving efficiency and safety of (future) transportation. There are chances of a number of possible attacks in VANET due to open nature of wireless medium. VANET generally consist of On Board Unit (OBU) and Roadside Units (RSUs). OBUs enable

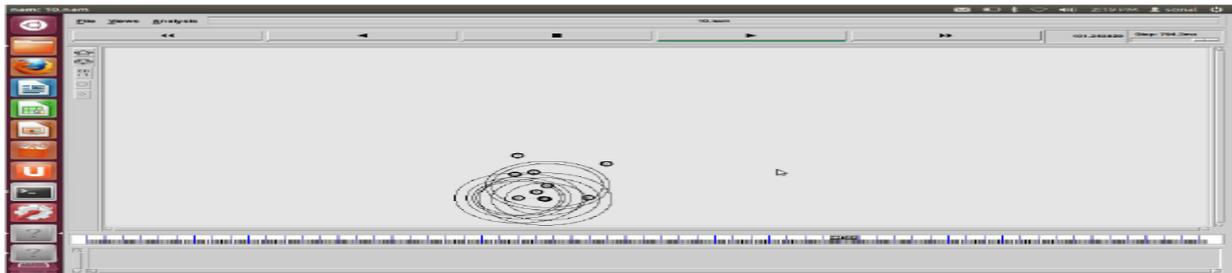


Figure 6: Running nam file of 10 nodes.

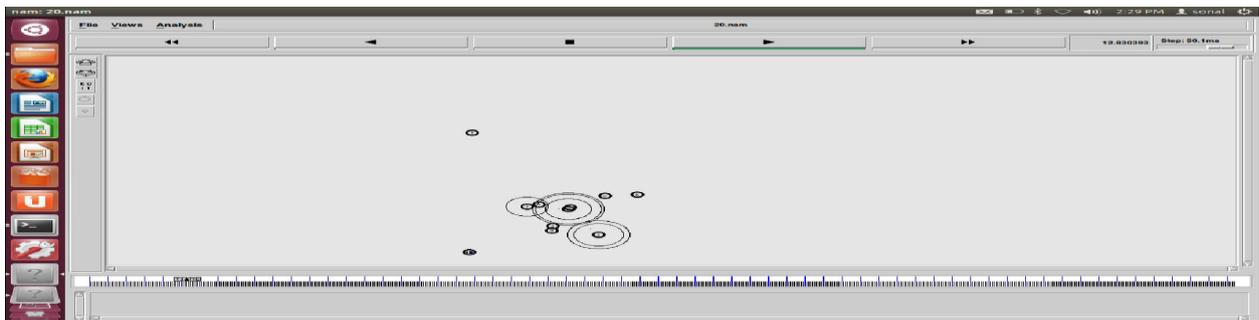


Figure 7: Running nam file of 20 nodes.

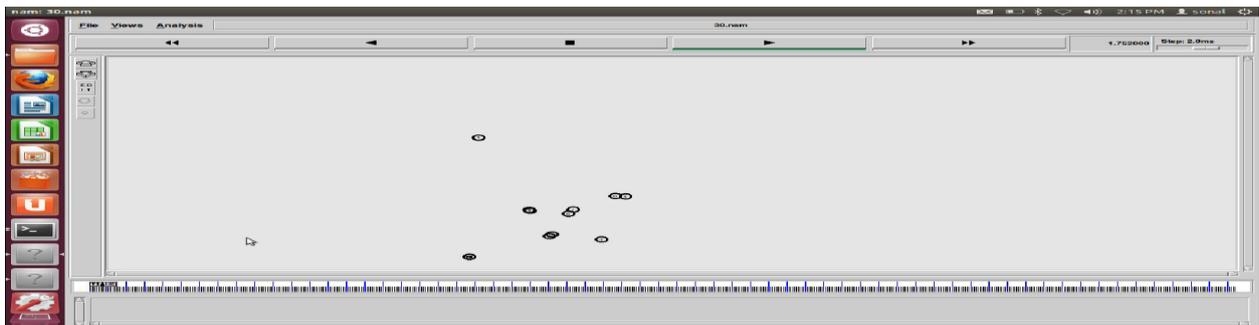


Figure 8: Running nam file of 30 nodes.

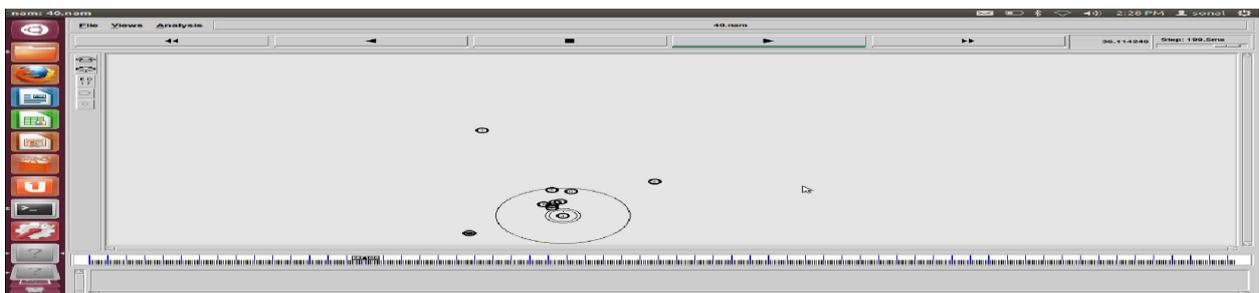
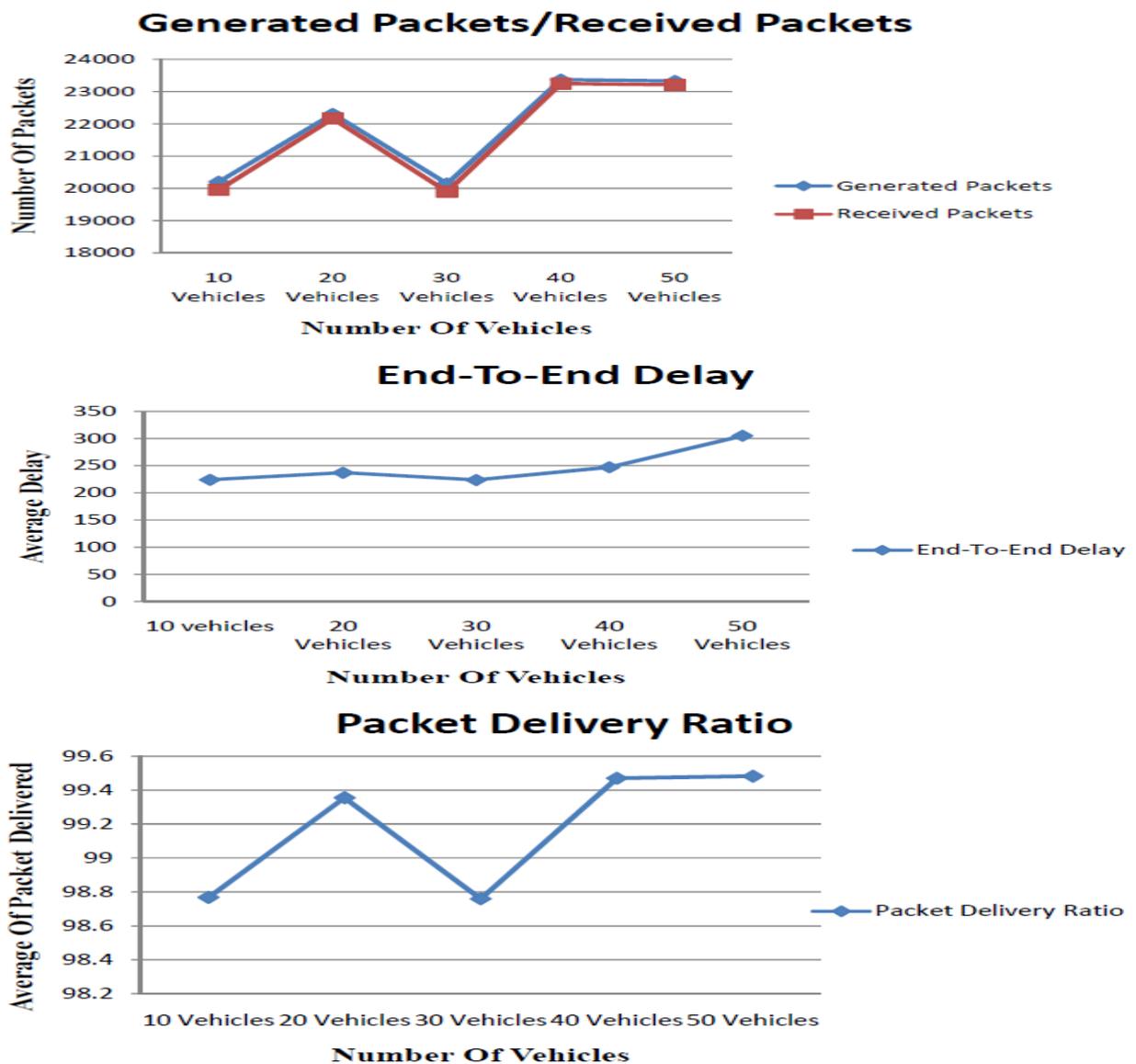


Figure 9: Running nam file of 40 nodes.



Figure 10: Running nam file of 50 nodes.



Vehicular Ad hoc Networks is a special kind of mobile ad hoc network to provide communication among nearby vehicles and between vehicles and nearby fixed equipments. VANETs are mainly used for improving efficiency and safety of (future) transportation. There are chances of a number of possible attacks in VANET due to open nature of wireless medium. VANET generally consist of On Board Unit (OBU) and Roadside Units (RSUs). OBUs enables short-range wireless ad hoc network to be formed between vehicles. Each vehicle comprises of

hardware unit for determining correct location information using GPS. Roadside Units (RSUs) are placed across the road for infrastructure communication. The number of RSU to be used depends upon the communication protocol.

VANET provide assistance to vehicle drivers for communication and coordination among themselves in order to avoid any critical situation through Vehicle to Vehicle communication e.g. road side accidents, traffic jams, speed control, free passage of emergency vehicles and unseen obstacles etc. Besides safety applications VANET also provide comfort applications to the road users. Due to the dynamic nature of nodes in VANET the routing of data packets is much complex. Several factors like the type of the road, daytime, weather, traffic density and even the driver himself affect the movements of vehicles on a road. Hence, the network topology changes frequently, and the routing protocol used has to adapt itself to these instantaneous changes continuously.

There is safety and non-safety messages are forwarded between the Vehicle to Vehicle (V2V) and Vehicle to Infrastructure (V2I) on this communication medium. Cooperation between the vehicles is essential to communicate with each other because of the short range of wireless communication medium. The attacker generates problems in the network by getting full access of communication medium due to open nature of the medium. Attacker may be authentic user/users (insiders) of the NETWORK that possess detail knowledge of network which they will be use for understanding the design and configuration of network. Therefore, it is easy for them to launch attacks and create more problem as compare to outsider attacker which is a kind of intruder which aims to misuse the protocols of the network. In the black hole attack, node is used to advertise a zero metric to all destinations, which become cause to all nodes around it in order to route data packets towards it. The AODV protocol is vulnerable to such kind of attack because of having network centric property, where each node of the network has to share their routing tables among each other. A malicious node may use the routing protocol to advertise itself as having the shortest path to the node whose packets it wants to intercept. In this work Black hole attack is efficiently removed by the extended AODV technique. By using this technique black hole attack is easy to detect, manage and recover. Here packet delivery ratio is increased and end-to-end delay gets decreased.

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